Pneumatic · 2-Finger Parallel Gripper · Sealed Grippers



Sizes 40 .. 200



Weight 0.25 kg .. 9.5 kg



Gripping force 125 N .. 6230 N



Stroke per finger 2 mm .. 25 mm



Workpiece weight 0.6 kg .. 22.1 kg

Application example



Sealed and extremely robust rotary gripping combination for use in tough environments such as foundries, grinding shops or forges

DPG-plus 125 2-Finger Parallel Gripper, with top fingers equipped with carbide clamping inserts SRU 35.1-180-3-4 Rotary Actuator in sealed IP67 version

Sealed Grippers

Despite the high moment load capabilities of the base jaws, this sealed 2-finger parallel gripper conforms to the IP 67 requirements and does not permit any substances from the working environment to penetrate the interior of the unit.

Area of application

The DPG-plus is ideally suited for the handling of rough or dirty workpieces. Its area of application extends from the loading and unloading of machines, such as in the case of sanitary blocks, grinding machines, lathes or milling machines, to handling tasks in painting plants, in powder-processing and underwater.



Robust interior multiple-tooth guidance

for the precise handling of all kinds of workpieces

Wiper seal on the outer round guide

for permanent, secure gripper sealing

High maximum load capabilities suitable for the use of long gripper fingers

Sealed 2-finger parallel gripper

is conform to IP67 requirements despite a high moment-load capabilities

Oval piston drive design

for maximum gripping forces

Mounting from two sides in three screw directions for universal and flexible gripper assembly

Air supply via hose-free direct connection or screw

for the flexible supply of compressed air in all automation systems

Compact dimensions

connections

for minimal interfering contours in handling



General information on the series

Working principle

Wedge-hook kinematics

Housing material

Aluminum alloy, hard-anodized

Base jaw material

Hardened steel

Actuation

Pneumatic, with filtered compressed air (10 μ m): Dry, lubricated or non-lubricated Pressure medium: Requirements on quality of the compressed air according to DIN ISO 8573-1: 6 4 4.

Warranty

24 months

Scope of delivery

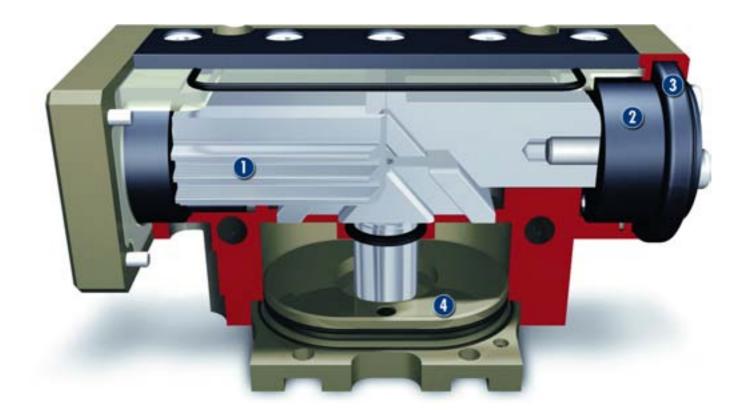
Centering sleeves, O-rings for direct connection, assembly and operating manual with manufacturer's declaration

Gripping force safety device

with either mechanical gripping force safety device or SDV-P pressure maintenance valve



Sectional diagram



- Inner base jaw
 (multiple-tooth guidance)
 for heavy moment loads
- Outer base jaw (round)
 providing a sealable, round surface
- Wiper seal for permanent, secure gripper sealing
- Oval piston
 with rod and wedge hook
 for power generation and transmission

Function description

The piston is moved up or down by means of compressed air. The angled active surfaces of the wedge hook produce a synchronized, parallel jaw movement.

Options and special information

Please note that an additional hose for bleeding or purging the air is essential for the gripper, i.e. it requires three hoses in total. See the assembly and operating manual for more detailed information.

Version with higher grip forces

When higher gripping forces are required



Accessories

Accessories from SCHUNK — the suitable supplement for maximum functionality, reliability and performance of all automation modules.

Centering sleeves



Fittings



MMS magnetic switches



KV/KA sensor cables



Quentes plastic inserts



HKI gripper pads





V sensor distributors



SDV-P pressure maintenance valves



• For the exact size of the required accessories, availability of this size and the designation and ID, please refer to the additional views at the end of the size in question.

You will find more detailed information on our accessory range in the "Accessories" catalog section.

General information on the series

Gripping force

is the arithmetic total of the gripping force applied to each base jaw at distance P (see illustration), measured from the upper edge of the gripper.

Finger length

is measured from the upper edge of the gripper housing in the direction of the main

Repeat accuracy

is defined as the spread of the limit position after 100 consecutive strokes.

Workpiece weight

The recommended workpiece weight is calculated for a force-type connection with a coefficient of friction of 0.1 and a safety factor of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit gripping.

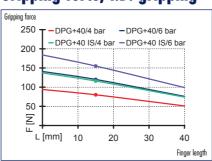
Closing and opening times

Closing and opening times are purely the times that the base jaws or fingers are in motion. Valve switching times, hose filling times or PLC reaction times are not included in the above times and must be taken into consideration when determining cycle times.

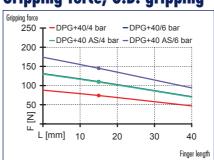




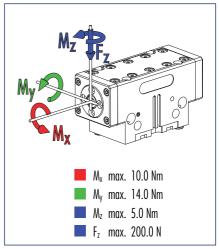
Gripping force, I.D. gripping



Gripping force, O.D. gripping

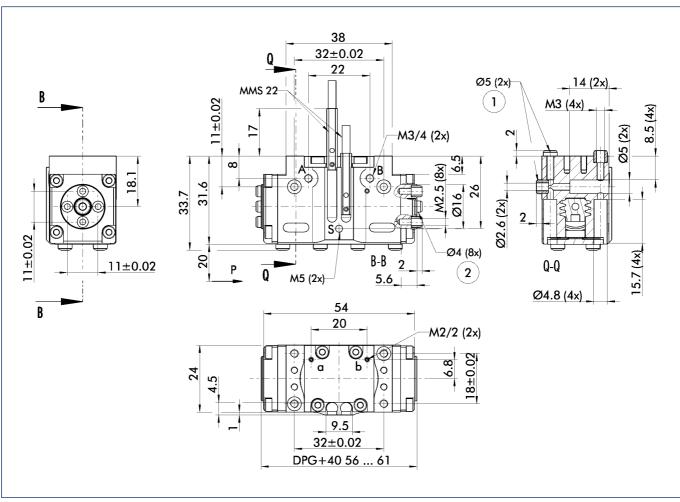


Finger load



Moments and forces apply per base jaw and may occur simultaneously. M_V may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

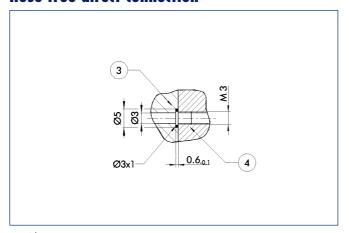
Description		DPG-plus 40	DPG-plus 40-AS	DPG-plus 40-IS
·	ID	0304291	0304293	0304295
Stroke per jaw	[mm]	2.5	2.5	2.5
Closing force	[N]	110.0	145.0	
Opening force	[N]	120.0		165.0
Min. spring force	[N]		35.0	45.0
Weight	[kg]	0.12	0.14	0.14
Recommended workpiece weight	[kg]	0.55	0.55	0.55
Air consumption per double stroke	[cm ³]	2.5	5.5	5.5
Minimum pressure	[bar]	2.5	4.0	4.0
Maximum pressure	[bar]	8.0	6.5	6.5
Nominal pressure	[bar]	6.0	6.0	6.0
Closing time	[s]	0.03	0.03	0.03
Opening time	[s]	0.03	0.05	0.05
Max. permitted finger length	[mm]	40.0	40.0	40.0
Max. permitted weight per finger	[kg]	0.1	0.1	0.1
IP rating		67	67	67
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0
Température ambiante max.	[°C]	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- (1) The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- S,s Air purge or ventilation hole
- (1) Gripper connection
- (2) Finger connection

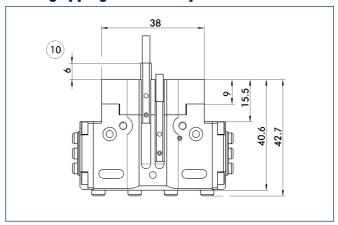
Hose-free direct connection



- 3 Adapter
- Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

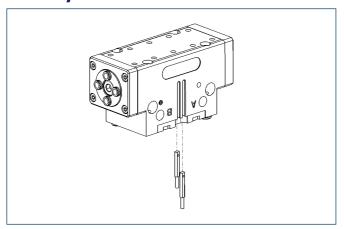
AS/IS gripping force safety device



(10) Projection only with AS version



Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

Description	ID	Recommended product	
MMS 22-S-M5-NPN	0301439		
MMS 22-S-M5-NPN-SA	0301449		
MMS 22-S-M5-PNP	0301438		
MMS 22-S-M5-PNP-SA	0301448		
MMS 22-S-M8-NPN	0301433		
MMS 22-S-M8-NPN-SA	0301443		
MMS 22-S-M8-PNP	0301432	•	
MMS 22-S-M8-PNP-SA	0301442		
MMSK 22-S-NPN	0301435		
MMSK 22-S-NPN-SA	0301445		
MMSK 22-S-PNP	0301434		
MMSK 22-S-PNP-SA	0301444		

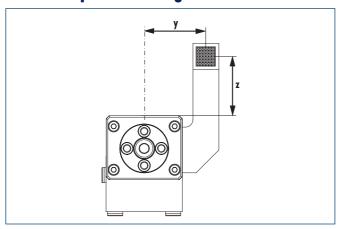
① Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

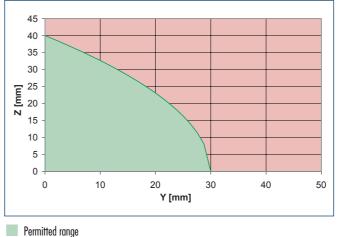
Extension cables for proximity switches/magnetic switches

Description	ID	
KA BG05-L 3P-0300	0301652	
KA BG08-L 3P-0300-PNP	0301622	
KA BW05-L 3P-0300	0301650	
KA BW08-L 3P-0300-NPN	0301602	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Maximum permitted finger offset

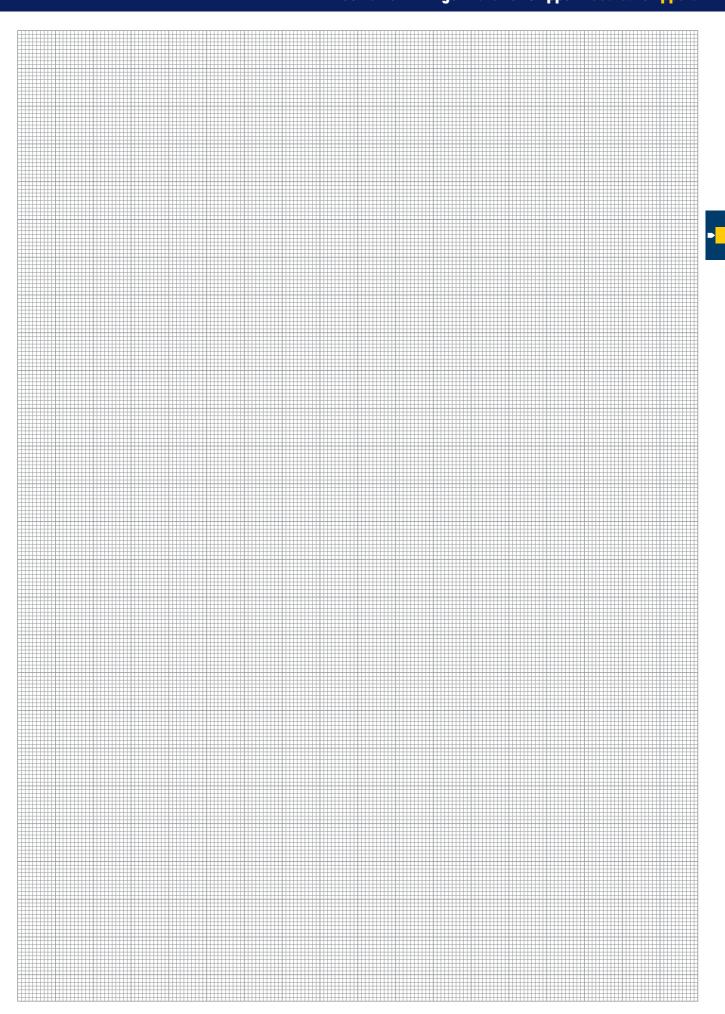




Non-permissible range

The curve applies to the basic version (stroke -1). For other versions, the curve will be parallel but offset in line with the max. permitted finger length.

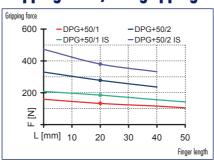




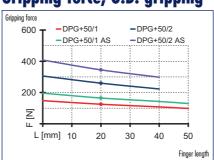




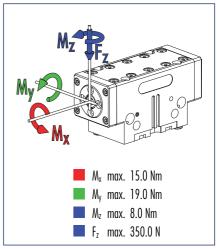
Gripping force, I.D. gripping



Gripping force, O.D. gripping



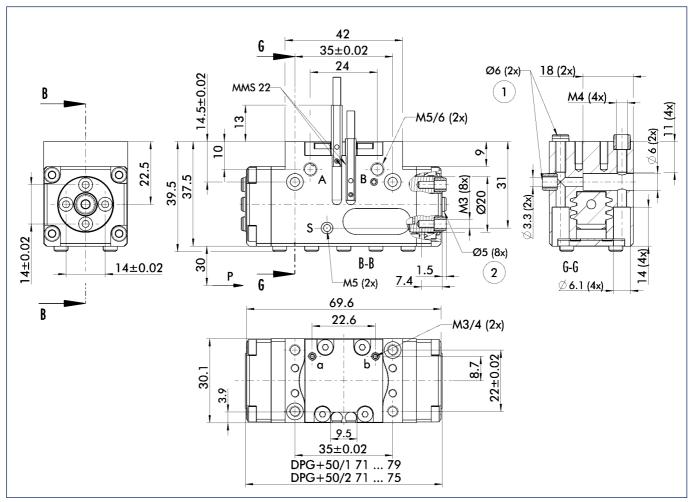
Finger load



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		DPG-plus 50-1	DPG-plus 50-2	DPG-plus 50-1-AS	DPG-plus 50-2-AS	DPG-plus 50-1-IS	DPG-plus 50-2-IS
	ID	0304301	0304302	0304303	0304304	0304305	0304306
Stroke per jaw	[mm]	4.0	2.0	4.0	2.0	4.0	2.0
Closing force	[N]	125.0	260.0	165.0	345.0		
Opening force	[N]	130.0	275.0			170.0	360.0
Min. spring force	[N]			40.0	85.0	40.0	85.0
Weight	[kg]	0.25	0.25	0.3	0.3	0.3	0.3
Recommended workpiece weight	[kg]	0.6	1.3	0.6	1.3	0.6	1.3
Air consumption per double stroke	[cm ³]	5.0	5.0	12.0	12.0	12.0	12.0
Minimum pressure	[bar]	2.5	2.5	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.03	0.03	0.03	0.03	0.05	0.05
Opening time	[s]	0.03	0.03	0.05	0.05	0.03	0.03
Max. permitted finger length	[mm]	50.0	40.0	50.0	40.0	50.0	40.0
Max. permitted weight per finger	[kg]	0.15	0.15	0.15	0.15	0.15	0.15
IP rating		67	67	67	67	67	67
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Température ambiante max.	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
OPTIONS and their charac	teristics						
KVZ for increased grip force	ID	0304307	0304308	0304309		0304300	
Description		DPG-plus 50-1-KVZ	DPG-plus 50-2-KVZ	DPG-plus 50-1-AS-KVZ		DPG-plus 50-1-IS-KVZ	
Closing force	[N]	225.0	470.0	265.0			
Opening force	[N]	235.0	505.0			275.0	
Weight	[kg]	0.29	0.29	0.34		0.34	
Maximum pressure	[bar]	6.0	6.0	6.0		6.0	
Air consumption per double stroke	[cm³]	10.0	10.0	17.0		17.0	
Max. permitted finger length	[mm]	40.0	30.0	30.0		30.0	

① Please note that an additional hose for bleeding ventilation or purging the air is essential for the gripper, i.e. it requires three hoses in total. See the assembly and operating manual for more detailed information.

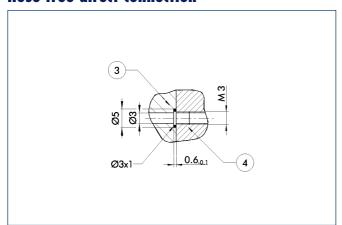


For finger connection, we recommend only using two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- S,s Air purge or ventilation hole
- 1) Gripper connection
- (2) Finger connection

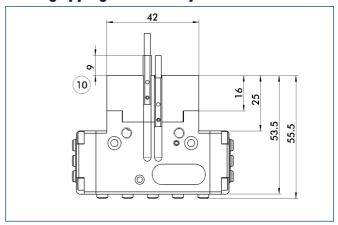
Hose-free direct connection



- 3 Adapter
- Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

AS/IS gripping force safety device

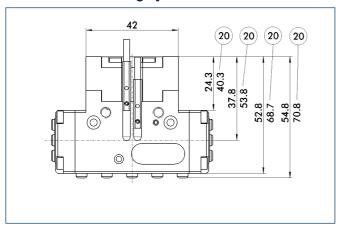


(10) Projection only with AS version



Pneumatic · 2-Finger Parallel Gripper · Sealed Grippers

KVZ for increased grip force

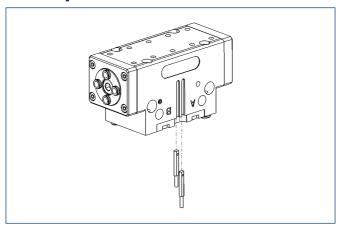


20 With AS / IS version

The KVZ grip-force cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. The full gripping force shown in the data table is sometimes only reached after a few hundred gripping cycles.



Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

•	,	•
Description	ID	Recommended product
MMS 22-S-M5-NPN	0301439	
MMS 22-S-M5-NPN-SA	0301449	
MMS 22-S-M5-PNP	0301438	
MMS 22-S-M5-PNP-SA	0301448	
MMS 22-S-M8-NPN	0301433	
MMS 22-S-M8-NPN-SA	0301443	
MMS 22-S-M8-PNP	0301432	•
MMS 22-S-M8-PNP-SA	0301442	
MMSK 22-S-NPN	0301435	
MMSK 22-S-NPN-SA	0301445	
MMSK 22-S-PNP	0301434	
MMSK 22-S-PNP-SA	0301444	

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

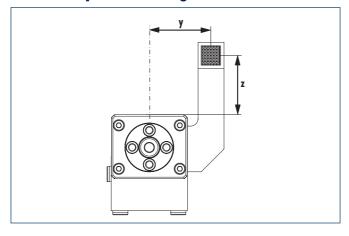
Extension cables for proximity switches/magnetic switches

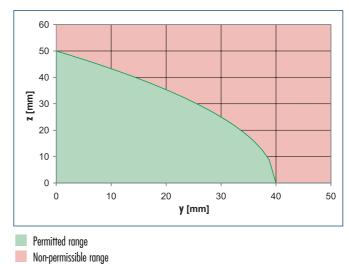
ID	
0301652	
0301622	
0301650	
0301602	
0301594	
9641116	
0301502	
0301495	
0301496	
0301497	
	0301652 0301622 0301650 0301602 0301594 9641116 0301502 0301495 0301496



Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Maximum permitted finger offset



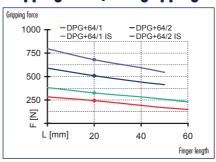


The curve applies to the basic version (stroke -1). For other versions, the curve will be parallel but offset in line with the max. permitted finger length.

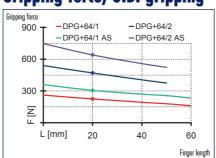




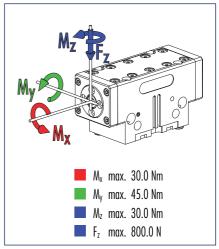
Gripping force, I.D. gripping



Gripping force, O.D. gripping



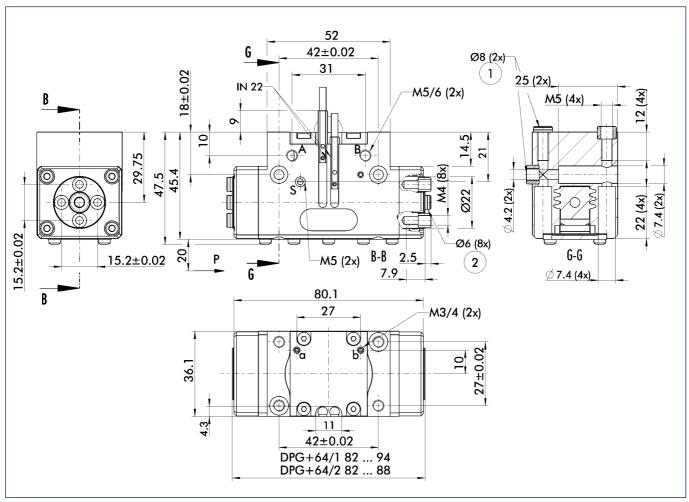
Finger load



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		DPG-plus 64-1	DPG-plus 64-2	DPG-plus 64-1-AS	DPG-plus 64-2-AS	DPG-plus 64-1-IS	DPG-plus 64-2-IS
·	ID	0304311	0304312	0304313	0304314	0304315	0304316
Stroke per jaw	[mm]	6.0	3.0	6.0	3.0	6.0	3.0
Closing force	[N]	225.0	470.0	305.0	640.0		
Opening force	[N]	240.0	500.0			320.0	670.0
Min. spring force	[N]			80.0	170.0	80.0	170.0
Weight	[kg]	0.39	0.39	0.46	0.46	0.46	0.46
Recommended workpiece weight	[kg]	1.1	2.3	1.1	2.3	1.1	2.3
Air consumption per double stroke	[cm ³]	9.0	9.0	24.0	24.0	24.0	24.0
Minimum pressure	[bar]	2.5	2.5	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.04	0.04	0.03	0.03	0.06	0.06
Opening time	[s]	0.04	0.04	0.06	0.06	0.03	0.03
Max. permitted finger length	[mm]	64.0	50.0	64.0	50.0	64.0	50.0
Max. permitted weight per finger	[kg]	0.3	0.3	0.3	0.3	0.3	0.3
IP rating		67	67	67	67	67	67
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Température ambiante max.	[° C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
OPTIONS and their charac	teristics						
KVZ for increased grip force	ID	0304317	0304318	0304319		0304310	
Description		DPG-plus 64-1-KVZ	DPG-plus 64-2-KVZ	DPG-plus 64-1-AS-KVZ		DPG-plus 64-1-IS-KVZ	
Closing force	[N]	405.0	850.0	485.0			
Opening force	[N]	440.0	915.0			520.0	
Weight	[kg]	0.47	0.47	0.55		0.55	
Maximum pressure	[bar]	6.0	6.0	6.0		6.0	
Air consumption per double stroke	[cm³]	9.0	9.0	24.0		24.0	
Max. permitted finger length	[mm]	50.0	40.0	40.0		40.0	

① Please note that an additional hose for bleeding ventilation or purging the air is essential for the gripper, i.e. it requires three hoses in total. See the assembly and operating manual for more detailed information.

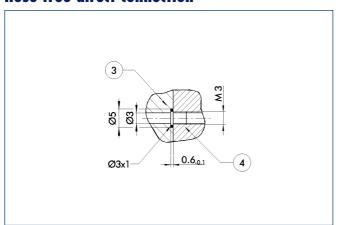


For finger connection, we recommend only using two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- S,s Air purge or ventilation hole
- 1) Gripper connection
- (2) Finger connection

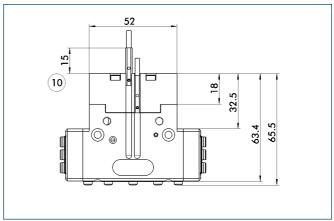
Hose-free direct connection



- 3 Adapter
- Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

AS/IS gripping force safety device

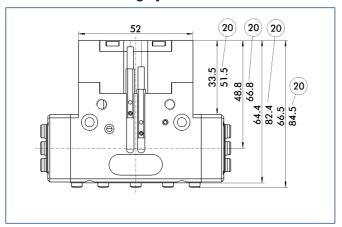


(10) Projection only with AS version



Pneumatic · 2-Finger Parallel Gripper · Sealed Grippers

KVZ for increased grip force

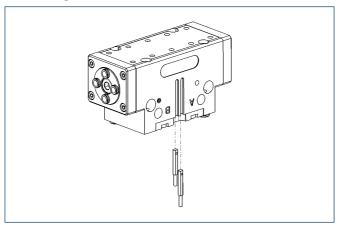


20 With AS / IS version

The KVZ grip-force cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. The full gripping force shown in the data table is sometimes only reached after a few hundred gripping cycles.



Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

Description	. ID	Recommended product	
MMS 22-S-M5-NPN	0301439		
MMS 22-S-M5-NPN-SA	0301449		
MMS 22-S-M5-PNP	0301438		
MMS 22-S-M5-PNP-SA	0301448		
MMS 22-S-M8-NPN	0301433		
MMS 22-S-M8-NPN-SA	0301443		
MMS 22-S-M8-PNP	0301432	•	
MMS 22-S-M8-PNP-SA	0301442		
MMSK 22-S-NPN	0301435		
MMSK 22-S-NPN-SA	0301445		
MMSK 22-S-PNP	0301434		
MMSK 22-S-PNP-SA	0301444		

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

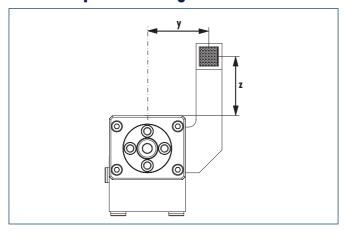
Extension cables for proximity switches/magnetic switches

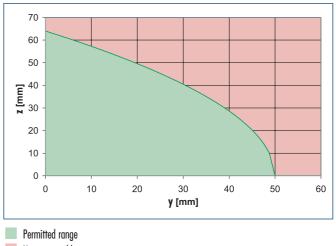
Description	ID	
KA BG05-L 3P-0300	0301652	
KA BG08-L 3P-0300-PNP	0301622	
KA BW05-L 3P-0300	0301650	
KA BW08-L 3P-0300-NPN	0301602	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	



① Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Maximum permitted finger offset





Non-permissible range

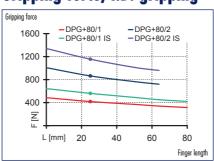
The curve applies to the basic version (stroke -1). For other versions, the curve will be parallel but offset in line with the max. permitted finger length.



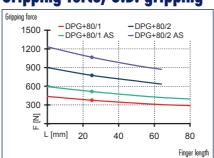




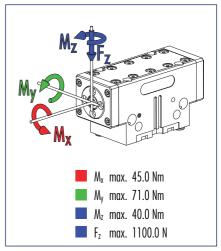
Gripping force, I.D. gripping



Gripping force, O.D. gripping



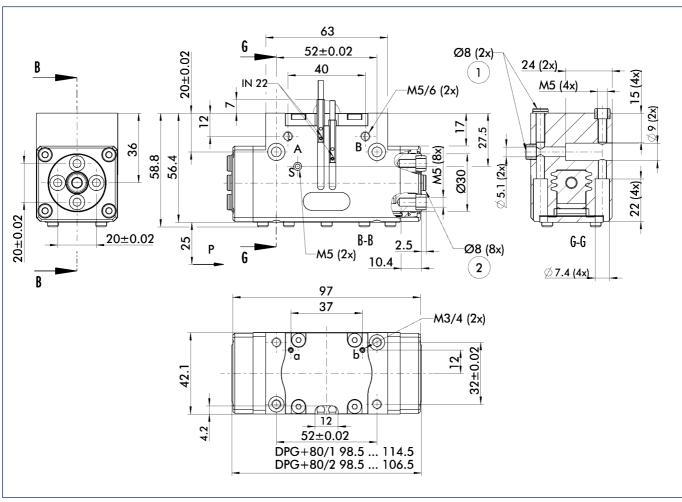
Finger load



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		DPG-plus 80-1	DPG-plus 80-2	DPG-plus 80-1-AS	DPG-plus 80-2-AS	DPG-plus 80-1-IS	DPG-plus 80-2-IS
	ID	0304321	0304322	0304323	0304324	0304325	0304326
Stroke per jaw	[mm]	8.0	4.0	8.0	4.0	8.0	4.0
Closing force	[N]	375.0	775.0	515.0	1065.0		
Opening force	[N]	415.0	860.0			555.0	1150.0
Min. spring force	[N]			140.0	290.0	140.0	290.0
Weight	[kg]	0.68	0.68	0.8	0.8	0.8	0.8
Recommended workpiece weight	[kg]	1.8	3.8	1.8	3.8	1.8	3.8
Air consumption per double stroke	[cm ³]	21.0	21.0	45.0	45.0	45.0	45.0
Minimum pressure	[bar]	2.5	2.5	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.05	0.05	0.04	0.04	0.07	0.07
Opening time	[s]	0.05	0.05	0.07	0.07	0.04	0.04
Max. permitted finger length	[mm]	80.0	64.0	80.0	64.0	80.0	64.0
Max. permitted weight per finger	[kg]	0.5	0.5	0.5	0.5	0.5	0.5
IP rating		67	67	67	67	67	67
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Température ambiante max.	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
OPTIONS and their charac	teristics						
KVZ for increased grip force	ID	0304327	0304328	0304329		0304320	
Description		DPG-plus 80-1-KVZ	DPG-plus 80-2-KVZ	DPG-plus 80-1-AS-KVZ		DPG-plus 80-1-IS-KVZ	
Closing force	[N]	675.0	1395.0	815.0			
Opening force	[N]	755.0	1550.0			895.0	
Weight	[kg]	0.85	0.85	0.95		0.95	
Maximum pressure	[bar]	6.0	6.0	6.0		6.0	
Air consumption per double stroke	[cm ³]	42.0	42.0	66.0		66.0	
Max. permitted finger length	[mm]	64.0	50.0	50.0		50.0	

⁽¹⁾ Please note that an additional hose for bleeding ventilation or purging the air is essential for the gripper, i.e. it requires three hoses in total. See the assembly and operating manual for more detailed information.

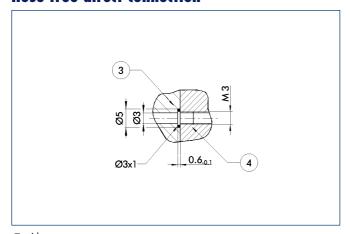


For finger connection, we recommend only using two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- S,s Air purge or ventilation hole
- 1) Gripper connection
- (2) Finger connection

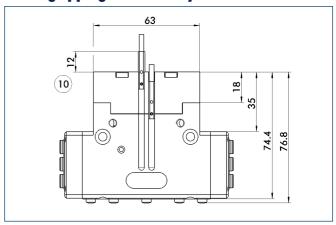
Hose-free direct connection



- 3 Adapter
- Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

AS/IS gripping force safety device



(10) Projection only with AS version

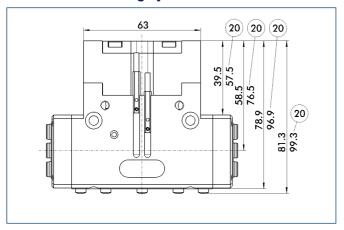
The mechanical gripping force safety device ensures a minimum gripping force even if there is a drop in pressure. This acts as closing force in the AS version, and as opening force in the IS version. In addition, the gripping force safety device can also be employed as a gripping force booster or for single-acting gripping.



371

Pneumatic · 2-Finger Parallel Gripper · Sealed Grippers

KVZ for increased grip force

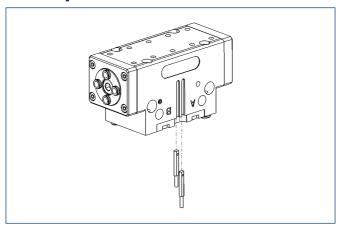


20 With AS / IS version

The KVZ grip-force cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. The full gripping force shown in the data table is sometimes only reached after a few hundred gripping cycles.



Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

Description	, ID	Recommended product
MMS 22-S-M5-NPN	0301439	
MMS 22-S-M5-NPN-SA	0301449	
MMS 22-S-M5-PNP	0301438	
MMS 22-S-M5-PNP-SA	0301448	
MMS 22-S-M8-NPN	0301433	
MMS 22-S-M8-NPN-SA	0301443	
MMS 22-S-M8-PNP	0301432	•
MMS 22-S-M8-PNP-SA	0301442	
MMSK 22-S-NPN	0301435	
MMSK 22-S-NPN-SA	0301445	
MMSK 22-S-PNP	0301434	
MMSK 22-S-PNP-SA	0301444	

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an

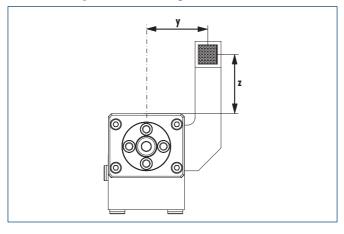
Extension cables for proximity switches/magnetic switches

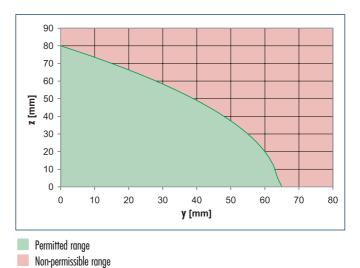
ID	
0301652	
0301622	
0301650	
0301602	
0301594	
9641116	
0301502	
0301495	
0301496	
0301497	
	0301652 0301622 0301650 0301602 0301594 9641116 0301502 0301495



① Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Maximum permitted finger offset



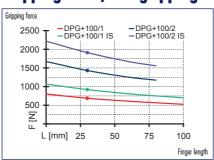


The curve applies to the basic version (stroke -1). For other versions, the curve will be parallel but offset in line with the max. permitted finger length.

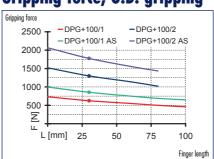




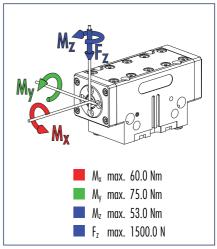
Gripping force, I.D. gripping



Gripping force, O.D. gripping



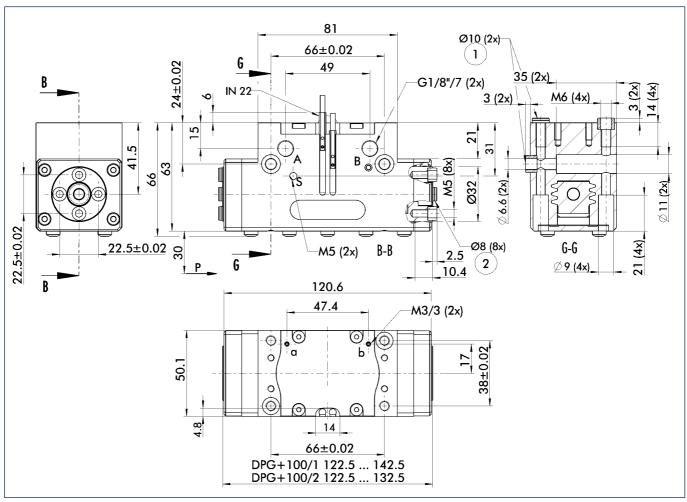
Finger load



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		DPG-plus 100-1	DPG-plus 100-2	DPG-plus 100-1-AS	DPG-plus 100-2-AS	DPG-plus 100-1-IS	DPG-plus 100-2-IS
	ID	0304331	0304332	0304333	0304334	0304335	0304336
Stroke per jaw	[mm]	10.0	5.0	10.0	5.0	10.0	5.0
Closing force	[N]	625.0	1300.0	855.0	1775.0		
Opening force	[N]	685.0	1430.0			915.0	1905.0
Min. spring force	[N]			230.0	475.0	230.0	475.0
Weight	[kg]	1.1	1.1	1.35	1.35	1.35	1.35
Recommended workpiece weight	[kg]	3.1	6.5	3.1	6.5	3.1	6.5
Air consumption per double stroke	[cm³]	40.0	40.0	85.0	85.0	85.0	85.0
Minimum pressure	[bar]	2.5	2.5	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.09	0.09	0.07	0.07	0.12	0.12
Opening time	[s]	0.09	0.09	0.12	0.12	0.07	0.07
Max. permitted finger length	[mm]	100.0	80.0	100.0	80.0	80.0	80.0
Max. permitted weight per finger	[kg]	0.95	0.95	0.95	0.95	0.95	0.95
IP rating		67	67	67	67	67	67
Min. ambient temperature	[° (]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Température ambiante max.	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
OPTIONS and their charac	teristics						
KVZ for increased grip force	ID	0304337	0304338	0304339		0304330	
Description		DPG-plus 100-1-KVZ	DPG-plus 100-2-KVZ	DPG-plus 100-1-AS-KVZ		DPG-plus 100-1-IS-KVZ	
Closing force	[N]	1125.0	2340.0	1355.0			
Opening force	[N]	1240.0	2560.0			1470.0	
Weight	[kg]	1.38	1.38	1.61		1.61	
Maximum pressure	[bar]	6.0	6.0	6.0		6.0	
Air consumption per double stroke	[cm³]	80.0	80.0	125.0		125.0	
Max. permitted finger length	[mm]	80.0	64.0	64.0		64.0	

⁽¹⁾ Please note that an additional hose for bleeding ventilation or purging the air is essential for the gripper, i.e. it requires three hoses in total. See the assembly and operating manual for more detailed information.

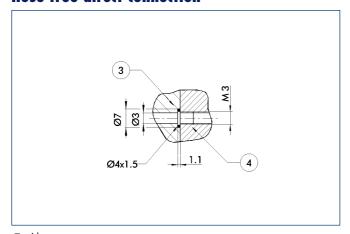


For finger connection, we recommend only using two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- S,s Air purge or ventilation hole
- (1) Gripper connection
- (2) Finger connection

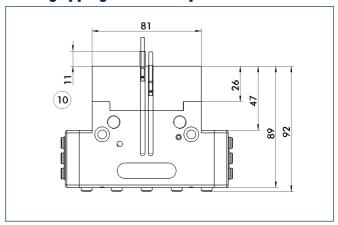
Hose-free direct connection



- 3 Adapter
- Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

AS/IS gripping force safety device

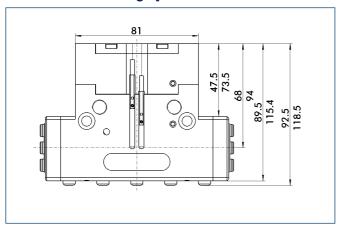


(10) Projection only with AS version



Pneumatic · 2-Finger Parallel Gripper · Sealed Grippers

KVZ for increased grip force

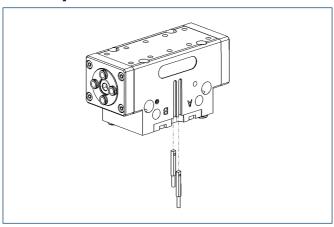


20 With AS / IS version

The KVZ grip-force cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. The full gripping force shown in the data table is sometimes only reached after a few hundred gripping cycles.



Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

•	,	•
Description	ID	Recommended product
MMS 22-S-M5-NPN	0301439	
MMS 22-S-M5-NPN-SA	0301449	
MMS 22-S-M5-PNP	0301438	
MMS 22-S-M5-PNP-SA	0301448	
MMS 22-S-M8-NPN	0301433	
MMS 22-S-M8-NPN-SA	0301443	
MMS 22-S-M8-PNP	0301432	•
MMS 22-S-M8-PNP-SA	0301442	
MMSK 22-S-NPN	0301435	
MMSK 22-S-NPN-SA	0301445	
MMSK 22-S-PNP	0301434	
MMSK 22-S-PNP-SA	0301444	

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an

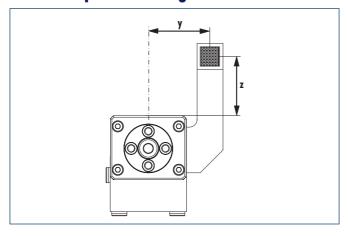
Extension cables for proximity switches/magnetic switches

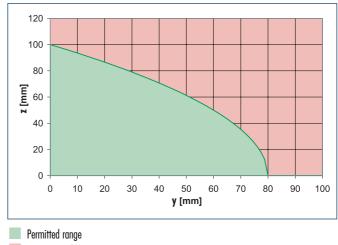
ID	
0301652	
0301622	
0301650	
0301602	
0301594	
9641116	
0301502	
0301495	
0301496	
0301497	
	0301652 0301622 0301650 0301602 0301594 9641116 0301502 0301495 0301496



① Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Maximum permitted finger offset





Non-permissible range

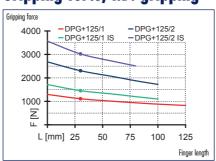
The curve applies to the basic version (stroke -1). For other versions, the curve will be parallel but offset in line with the max. permitted finger length.



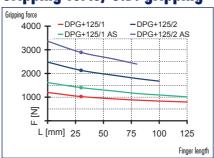




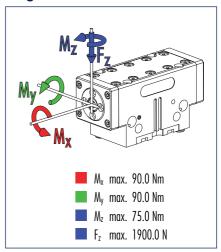
Gripping force, I.D. gripping



Gripping force, O.D. gripping



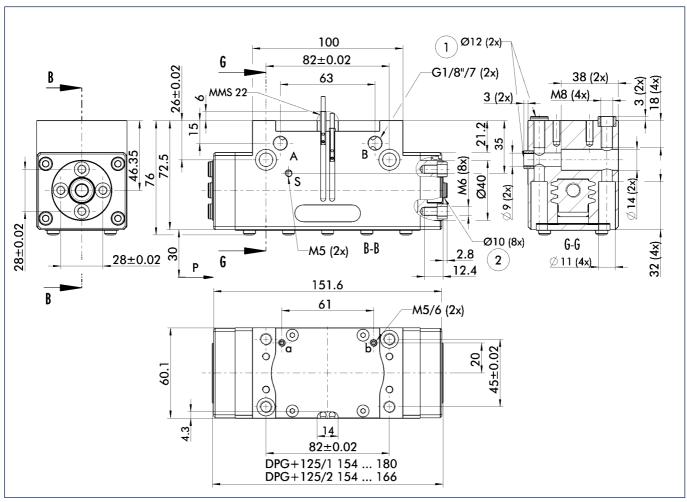
Finger load



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		DPG-plus 125-1	DPG-plus 125-2	DPG-plus 125-1-AS	DPG-plus 125-2-AS	DPG-plus 125-1-IS	DPG-plus 125-2-IS
	ID	0304341	0304342	0304343	0304344	0304345	0304346
Stroke per jaw	[mm]	13.0	6.0	13.0	6.0	13.0	6.0
Closing force	[N]	1025.0	2130.0	1400.0	2890.0		
Opening force	[N]	1110.0	2300.0			1485.0	3060.0
Min. spring force	[N]			375.0	760.0	375.0	760.0
Weight	[kg]	1.9	1.9	2.35	2.35	2.35	2.35
Recommended workpiece weight	[kg]	5.1	10.6	5.1	10.6	5.1	10.6
Air consumption per double stroke	[cm³]	81.0	81.0	158.0	158.0	158.0	158.0
Minimum pressure	[bar]	2.5	2.5	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.13	0.13	0.11	0.11	0.16	0.16
Opening time	[s]	0.13	0.13	0.16	0.16	0.11	0.11
Max. permitted finger length	[mm]	125.0	100.0	125.0	80.0	100.0	80.0
Max. permitted weight per finger	[kg]	1.75	1.75	1.75	1.75	1.75	1.75
IP rating		67	67	67	67	67	67
Min. ambient temperature	[° (]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Température ambiante max.	[° (]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
OPTIONS and their charac							
KVZ for increased grip force	ID	0304347	0304348	0304349		0304340	
Description		DPG-plus 125-1-KVZ	DPG-plus 125-2-KVZ			DPG-plus 125-1-IS-KVZ	
Closing force	[N]	1845.0	3835.0	2220.0			
Opening force	[N]	2000.0	4140.0			2375.0	
Weight	[kg]	2.4	2.4	2.9		2.9	
Maximum pressure	[bar]	6.0	6.0	6.0		6.0	
Air consumption per double stroke	[cm³]	162.0	162.0	239.0		239.0	
Max. permitted finger length	[mm]	80.0	64.0	64.0		64.0	

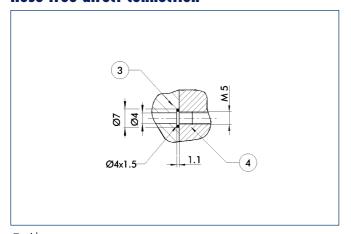
⁽¹⁾ Please note that an additional hose for bleeding ventilation or purging the air is essential for the gripper, i.e. it requires three hoses in total. See the assembly and operating manual for more detailed information.



For finger connection, we recommend only using two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- (i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- S,s Air purge or ventilation hole
- 1) Gripper connection
- (2) Finger connection

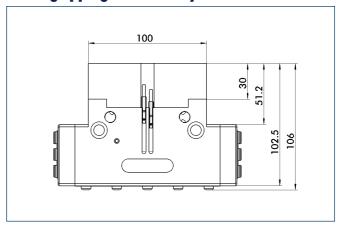
Hose-free direct connection



- 3 Adapter
- Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

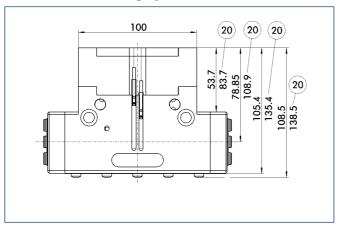
AS/IS gripping force safety device





Pneumatic · 2-Finger Parallel Gripper · Sealed Grippers

KVZ for increased grip force

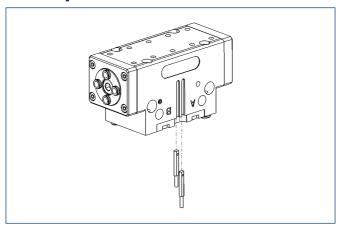


20 With AS / IS version

The KVZ grip-force cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. The full gripping force shown in the data table is sometimes only reached after a few hundred gripping cycles.



Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

Description	. ID	Recommended product	
MMS 22-S-M5-NPN	0301439		
MMS 22-S-M5-NPN-SA	0301449		
MMS 22-S-M5-PNP	0301438		
MMS 22-S-M5-PNP-SA	0301448		
MMS 22-S-M8-NPN	0301433		
MMS 22-S-M8-NPN-SA	0301443		
MMS 22-S-M8-PNP	0301432	•	
MMS 22-S-M8-PNP-SA	0301442		
MMSK 22-S-NPN	0301435		
MMSK 22-S-NPN-SA	0301445		
MMSK 22-S-PNP	0301434		
MMSK 22-S-PNP-SA	0301444		

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

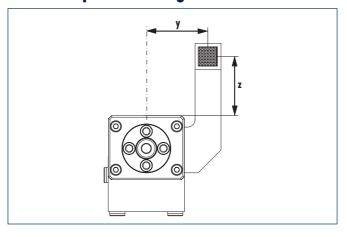
Extension cables for proximity switches/magnetic switches

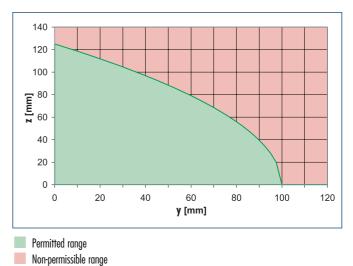
Description	ID	
KA BG05-L 3P-0300	0301652	
KA BG08-L 3P-0300-PNP	0301622	
KA BW05-L 3P-0300	0301650	
KA BW08-L 3P-0300-NPN	0301602	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	



Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Maximum permitted finger offset



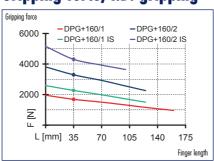


The curve applies to the basic version (stroke -1). For other versions, the curve will be parallel but offset in line with the max. permitted finger length.

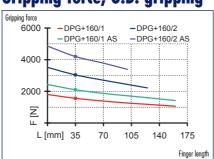




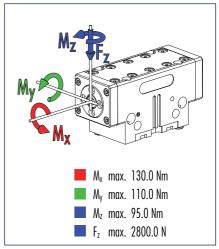
Gripping force, I.D. gripping



Gripping force, O.D. gripping



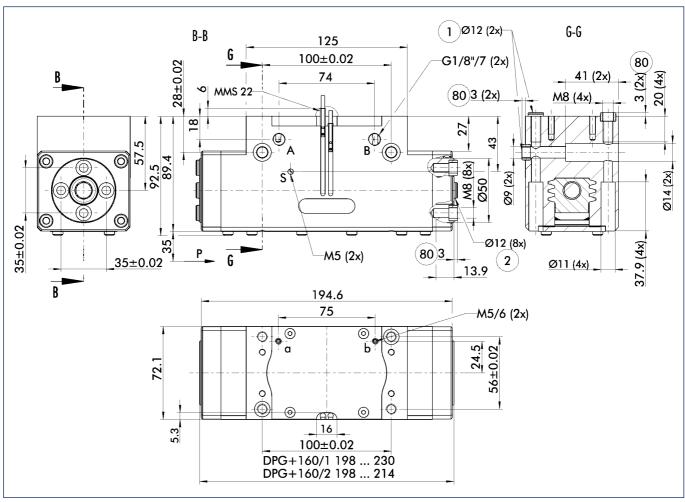
Finger load



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		DPG-plus 160-1	DPG-plus 160-2	DPG-plus 160-1-AS	DPG-plus 160-2-AS	DPG-plus 160-1-IS	DPG-plus 160-2-IS
	ID	0304351	0304352	0304353	0304354	0304355	0304356
Stroke per jaw	[mm]	16.0	8.0	16.0	8.0	16.0	8.0
Closing force	[N]	1560.0	3040.0	2100.0	4200.0		
Opening force	[N]	1680.0	3290.0			2220.0	4450.0
Min. spring force	[N]			540.0	1160.0	540.0	1160.0
Weight	[kg]	3.65	3.65	4.65	4.65	4.65	4.65
Recommended workpiece weight	[kg]	7.8	15.2	7.8	15.2	7.8	15.2
Air consumption per double stroke	[cm³]	157.0	157.0	265.0	265.0	265.0	265.0
Minimum pressure	[bar]	2.5	2.5	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.19	0.19	0.16	0.16	0.33	0.33
Opening time	[s]	0.19	0.19	0.33	0.33	0.16	0.16
Max. permitted finger length	[mm]	160.0	125.0	160.0	100.0	125.0	100.0
Max. permitted weight per finger	[kg]	3.0	3.0	3.0	3.0	3.0	3.0
IP rating		67	67	67	67	67	67
Min. ambient temperature	[°[]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Température ambiante max.	[° (]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
OPTIONS and their charac							
KVZ for increased grip force	ID	0304357	0304358	0304359		0304350	
Description		DPG-plus 160-1-KVZ	DPG-plus 160-2-KVZ	DPG-plus 160-1-AS-KVZ		DPG-plus 160-1-IS-KVZ	
Closing force	[N]	2810.0	5470.0	3350.0			
Opening force	[N]	3025.0	5920.0			3520.0	
Weight	[kg]	5.8	5.8	8.0		8.0	
Maximum pressure	[bar]	6.0	6.0	6.0		6.0	
Air consumption per double stroke	[cm³]	314.0	314.0	422.0		422.0	
Max. permitted finger length	[mm]	100.0	80.0	80.0		80.0	

① Please note that an additional hose for bleeding ventilation or purging the air is essential for the gripper, i.e. it requires three hoses in total. See the assembly and operating manual for more detailed information.

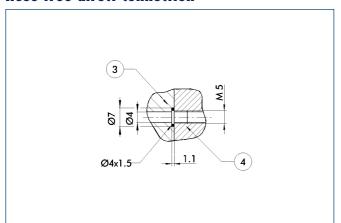


For finger connection, we recommend only using two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- S,s Air purge or ventilation hole
- (1) Gripper connection
- (2) Finger connection
- depth of the centering sleeve hole in the matching part

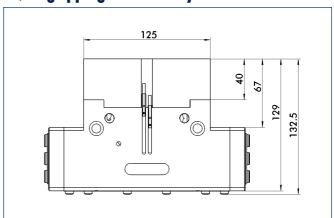
Hose-free direct connection



- 3 Adapter
- 4 Grippe

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

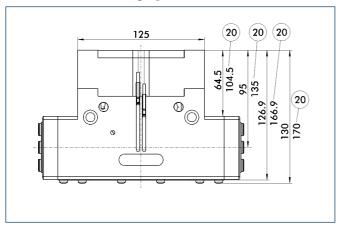
AS/IS gripping force safety device





Pneumatic · 2-Finger Parallel Gripper · Sealed Grippers

KVZ for increased grip force

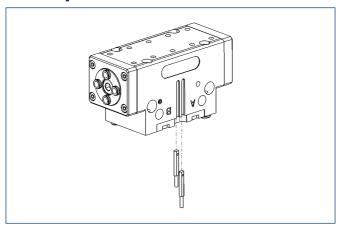


20 With AS / IS version

The KVZ grip-force cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. The full gripping force shown in the data table is sometimes only reached after a few hundred gripping cycles.



Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

•	,	•
Description	ID	Recommended product
MMS 22-S-M5-NPN	0301439	
MMS 22-S-M5-NPN-SA	0301449	
MMS 22-S-M5-PNP	0301438	
MMS 22-S-M5-PNP-SA	0301448	
MMS 22-S-M8-NPN	0301433	
MMS 22-S-M8-NPN-SA	0301443	
MMS 22-S-M8-PNP	0301432	•
MMS 22-S-M8-PNP-SA	0301442	
MMSK 22-S-NPN	0301435	
MMSK 22-S-NPN-SA	0301445	
MMSK 22-S-PNP	0301434	
MMSK 22-S-PNP-SA	0301444	

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

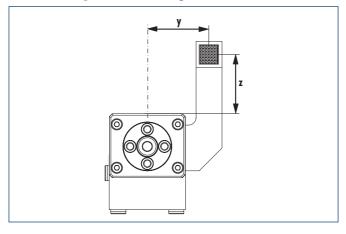
Extension cables for proximity switches/magnetic switches

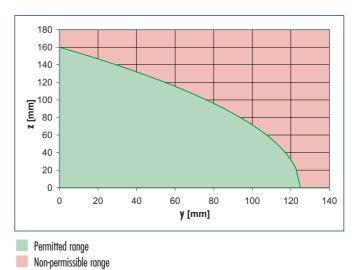
ID	
0301652	
0301622	
0301650	
0301602	
0301594	
9641116	
0301502	
0301495	
0301496	
0301497	
	0301652 0301622 0301650 0301602 0301594 9641116 0301502 0301495 0301496



Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Maximum permitted finger offset



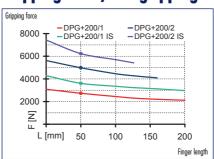


The curve applies to the basic version (stroke -1). For other versions, the curve will be parallel but offset in line with the max. permitted finger length.

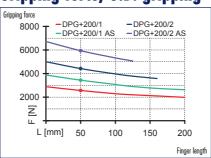




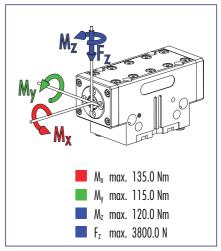
Gripping force, I.D. gripping



Gripping force, O.D. gripping



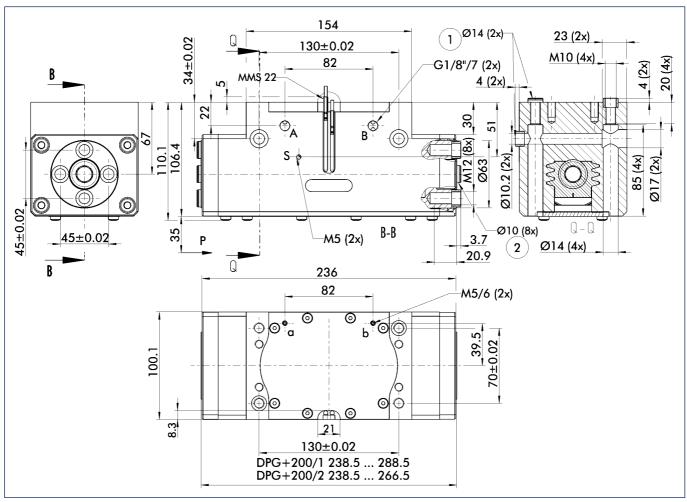
Finger load



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		DPG-plus 200-1	DPG-plus 200-2	DPG-plus 200-1-AS	DPG-plus 200-2-AS	DPG-plus 200-1-IS	DPG-plus 200-2-IS
	ID	0304361	0304362	0304363	0304364	0304365	0304366
Stroke per jaw	[mm]	25.0	14.0	25.0	14.0	25.0	14.0
Closing force	[N]	2565.0	4420.0	3440.0	5940.0		
Opening force	[N]	2730.0	4970.0			3605.0	6490.0
Min. spring force	[N]			875.0	1520.0	875.0	1520.0
Weight	[kg]	7.3	7.3	9.5	9.5	9.5	9.5
Recommended workpiece weight	[kg]	12.8	22.1	12.8	22.1	12.8	22.1
Air consumption per double stroke	[cm ³]	390.0	390.0	635.0	635.0	635.0	635.0
Minimum pressure	[bar]	2.5	2.5	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.45	0.45	0.4	0.4	0.8	0.8
Opening time	[s]	0.45	0.45	0.8	0.8	0.4	0.4
Max. permitted finger length	[mm]	200.0	160.0	200.0	125.0	160.0	125.0
Max. permitted weight per finger	[kg]	5.5	5.5	5.5	5.5	5.5	5.5
IP rating		67	67	67	67	67	67
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Température ambiante max.	[°(]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.02	0.02	0.02	0.02	0.02	0.02

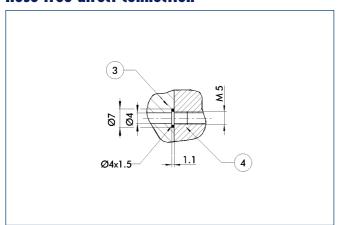
⁽¹⁾ Please note that an additional hose for bleeding ventilation or purging the air is essential for the gripper, i.e. it requires three hoses in total. See the assembly and operating manual for more detailed information.



For finger connection, we recommend only using two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- (i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- S,s Air purge or ventilation hole
- 1) Gripper connection
- (2) Finger connection

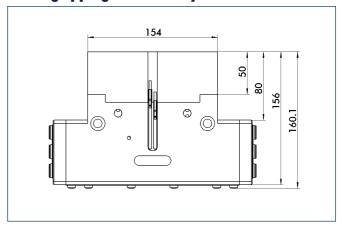
Hose-free direct connection



- 3 Adapter
- 4 Grippe

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

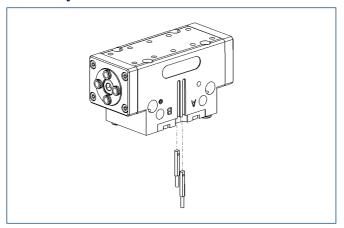
AS/IS gripping force safety device





Pneumatic · 2-Finger Parallel Gripper · Sealed Grippers

Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

Description	ID	Recommended product	
MMS 22-S-M5-NPN	0301439	•	
MMS 22-S-M5-NPN-SA	0301449		
MMS 22-S-M5-PNP	0301438		
MMS 22-S-M5-PNP-SA	0301448		
MMS 22-S-M8-NPN	0301433		
MMS 22-S-M8-NPN-SA	0301443		
MMS 22-S-M8-PNP	0301432	•	
MMS 22-S-M8-PNP-SA	0301442		
MMSK 22-S-NPN	0301435		
MMSK 22-S-NPN-SA	0301445		
MMSK 22-S-PNP	0301434		
MMSK 22-S-PNP-SA	0301444		

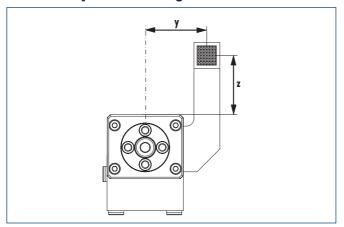
① Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

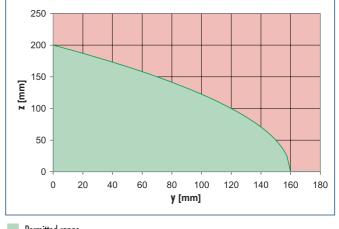
Extension cables for proximity switches/magnetic switches

Description	ID	
KA BG05-L 3P-0300	0301652	
KA BG08-L 3P-0300-PNP	0301622	
KA BW05-L 3P-0300	0301650	
KA BW08-L 3P-0300-NPN	0301602	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Maximum permitted finger offset





Permitted range
Non-permissible range

The curve applies to the basic version (stroke -1). For other versions, the curve will be parallel but offset in line with the max. permitted finger length.



