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#### B3S & B3W ELECTRIC B3S & B3W ELE

**B3S SCREW-DRIVE** 

**B3W BELT-DRIVE** 

LINEAR SOLUTIONS MADE EASY

### **Tolomatic B3S & B3W Electric Rodless Actuators**



### The Power to Move Heavy Loads

The B3S and B3W electric rodless actuators have very large moment and load carrying capacities. The sealed recirculating ball bearing design makes it an excellent choice for challenging environments. For even higher capacity (loads up to 3,629 kg.) choose the Dual 180° Carrier and add an auxiliary carrier. Both actuators utilize a patented internal re-circulating ball bearing guidance system that provides extremely long life. These actuators are capable of carrying loads up to 3,629 kg [8,000 lbs].

	ARISON OF SCREW	V DRIVE ACTUATO	KS	
	TRS	B3S	MXE-S	MXE-P
			11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	410
Features:	Dual profile rail bearing actuator	High load and bending moment capacities	Basic guidance and support	High load and bending moment capacities
Load up to: (with options)	6.0 kN [1,356 lbf]	35.6 kN [8,000 lbf]	4.6 kN [1,040 lbf]	11.5 kN [2,584 lbf]
Thrust up to:	2.5 kN [562 lbf]	12 kN [2,700 lbf]	19.1 kN [4,300 lbf]	19.1 kN [4,300 lbf]
Speed up to:	0.91 m/sec [36 in/sec]	1.5 m/sec [60 in/sec]	1.5 m/sec [60 in/sec]	1.5 m/sec [60 in/sec]
Stroke Length up to:	1.1 m [43 in]	4.5 m [179 in]	4.5 m [178 in]	4.5m [178 in]
Screw/Nut Type	Solid & Ball	Solid & Ball	Solid & Ball	Solid & Ball
	www.tolor	natic.com for complete inf	ormation, search by literatu	ıre number:
Literature Number:	3600-4222	3600-4176	8300-4000	8300-4000

#### **A COMPARISON OF SCREW DRIVE ACTUATORS**

(Not all models deliver ALL maximum values listed, i.e.: Maximum thrust may not be available with maximum speed)

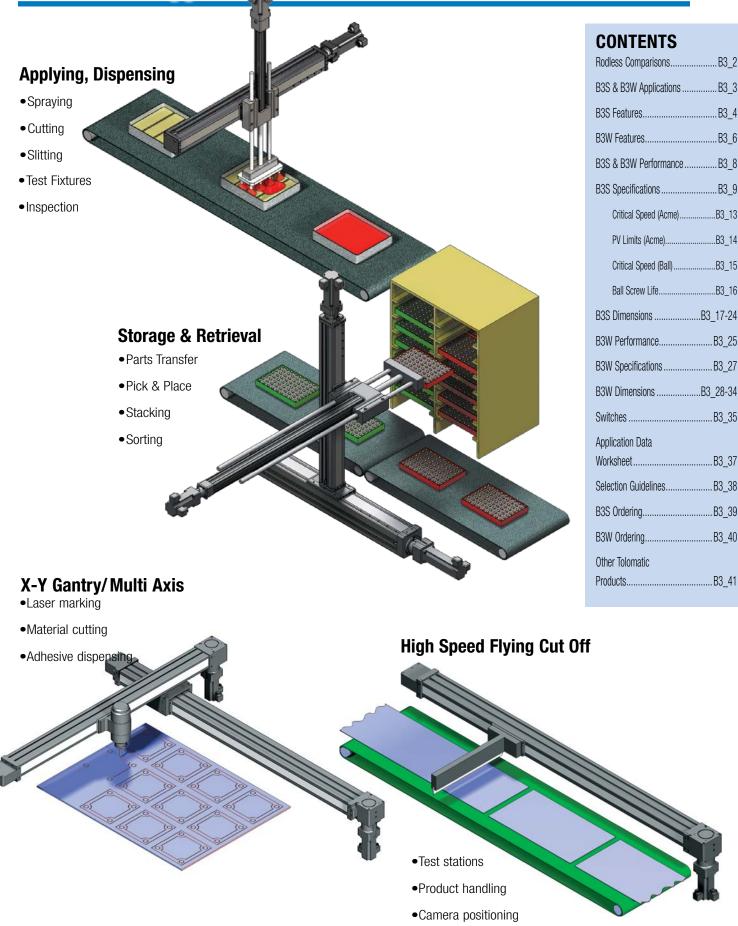
### A COMPARISON OF BELT DRIVE ACTUATORS

	B3W	MXB-U	MXB-S	МХВ-Р
Features:	High load and bending moment capacities	Basic thrust, requires exter- nal guidance and support	Medium load and bending moment capacities	High load and bending moment capacities
Load up to: (with options)	35.6 kN [8,000 lbf]	NA	4.6 kN [1,040 lbf]	11.5 kN [2,584 lbf]
Thrust up to:	1.4 kN [325 lbf]	1.9 kN [418 lbf]	1.9 kN [418 lbf]	1.9 kN [418 lbf]
Speed up to:	5.1 m/sec [200 in/sec]	5.1 m/sec [200 in sec]	2.5 m/sec [100 in sec]	3.9 m/sec [150 in/sec]
Stroke Length up to:	14.6 m [574 in]	10.5 m [414 in]	10.5 m [414 in]	10.5 m [414 in]
	www.toloi	matic.com for complete inf	ormation, search by literatu	re number:
Literature Number:	3600-4176	8500-4000	8500-4000	8500-4000

(Not all models deliver ALL maximum values listed, i.e.: Maximum thrust may not be available with maximum speed)



### **B3S & B3W Applications**



Tolomatic EXCELLENCE IN MOTION

# **B3S RODLESS SCREW DRIVE ACTUATOR**

# ENDURANCE TECHNOLOGY sealed for maximum durab

Endurance Technology features are designed for maximum durability to

A Tolomatic Design Principle

The B3S rodless screw-drive electric actuator is designed for carrying moderate to heavy loads with large bending moment capacity. The B3S utilizes an integral recirculating ball bearing guidance system that provides durable performance and extremely long life. Choose from multiple screw technologies for thrust up 12 kN [2,700 lbf]. Built-to-order in stroke lengths up to 10.6 m [416 inches].

#### **LOAD-BEARING CARRIER DESIGN**

Load and moments are transmitted directly to the actuator body

#### FORMED END CAP WIPERS

Prevent contaminants from entering the sealing band area to protect internal components

B3S

## **INTERNAL BUMPERS**

Bumpers protect the screw and nut assembly from damage at end of stroke

### STAINLESS STEEL SEALING BAND

- Prevents contaminants from entering the screw and nut area for extended performance
- Fatigue resistant stainless steel bands are specifically made to offer long life and will not elongate
- Provides IP44 protection for bearings and screw nut

#### **MULTIPLE SCREW TECHNOLOGIES**

#### YOU CAN CHOOSE:

backlash available

· Solid nuts of engineered resins offer quiet performance at the lowest cost; anti-backlash available

Ball nuts offer positioning accuracy

and repeatability with longer life; low-





# Tolomatic ... MAXIMUM DURABILITY

#### **SCREW SUPPORT BEARINGS**

Unique high thrust bearing assembly design eliminates runout and isolates the linear forces from the drive shaft

#### LIGHTWEIGHT ALUMINUM DESIGN

- •Black anodized extrusion design is optimized for rigidity and strength
- External switch channels on both sides allow easy placement and adjustment of position indicating switches

#### RECIRCULATING BALL BEARING SYSTEM



- Unique design incorporates hardened steel raceways integral to the aluminum extrusion
- Bearing surfaces are adjusted at the factory for optimum preload and smooth performance
- Recirculating ball bearing system provides guidance, high efficiency and durability

#### MOTOR ORIENTATION

#### YOU CAN CHOOSE:

- Inline option directly couples the driving shaft and is typically a onepiece housing construction for optimum alignment and support of the motor
- Reverse-parallel option minimizes the overall length and offers a belt reduction drive with a 1:1 or 2:1 ratio

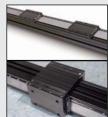
#### **YOUR MOTOR HERE**

#### YOU CAN CHOOSE:

- •Specify the device to be installed and actuator ships with proper mounting hardware
- •Specify and ship your device to Tolomatic for factory installation
- •Motor or gearbox supplied and installed by Tolomatic

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### **OPTIONS**





- •AUXILIARY CARRIER doubles the load capacity and increases pitch and yaw bending moment capacities
- **DUAL 180° CARRIER** doubles the load capacity, increases roll and yaw bending moment capacities and offers a wide mounting platform

### **MOUNTING OPTIONS**

- SURFACE MOUNT two t-slots are integral on the entire underside of the actuator body for direct mounting
- **TUBE SUPPORTS** provide intermediate support of the actuator body throughout long stroke lengths
- **MOUNTING PLATES** provide intermediate support of the actuator body throughout long stroke lengths

#### METRIC OPTION

Provides metric tapped holes for mounting of load to carrier and of actuator to mating surfaces

#### SWITCHES

Styles include: reed, hall-effect or triac. Select either 5 m potted cable with flying leads or 150 mm to quickdisconnect coupler with mating 5 m cable



# **B3W RODLESS BELT-DRIVE ACTUATOR**

Endurance Technology features are designed for maximum durability to sm provide extended service life.

**ENDURANCE TECHNOLOGY** A Tolomatic Design Principle

The B3W rodless belt-drive electric actuator is designed for carrying moderate to heavy loads at moderate to high speeds with large bending moment capacity. The B3W utilizes an integral recirculating ball bearing guidance system that provides durable performance and extremely long life. The B3W belt-driven actuator features speeds up to 5.1 m/ sec [200 in/sec]. Built-to-order in stroke lengths up to 5.3 m [207 inches].

#### **YOUR MOTOR HERE**

#### YOU CAN CHOOSE:

•Specify the device to be installed and actuator ships with proper mounting hardware

•Specify and ship your device to Tolomatic for factory installation

•Motor or gearbox supplied and installed by Tolomatic

#### STAINLESS STEEL SEALING BAND

• Prevents contaminants from entering the screw and nut area for extended performance

• Fatigue resistant stainless steel bands are specifically made to offer long life and will not elongate

• Provides IP44 protection for bearings and screw nut

#### **MOTOR ORIENTATION**

#### YOU CAN CHOOSE:

- Direct drive option directly couples the driving shaft and is typically a one-piece housing construction for optimum alignment and support of the motor
- Reduction drive option minimizes the overall length and offers a belt reduction drive with a 1:1 or 2:1 ratio

#### LIGHTWEIGHT ALUMINUM DESIGN

- Black anodized extrusion design is optimized for rigidity and strength
- External switch channels on both sides allow easy placement and adjustment of position indicating switches

#### **OVERSIZED PULLEY BEARINGS**

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Drive shaft assembly incorporates sealed ball bearings for complete support of the increased belt tension at high speeds

#### INTERNAL BUMPERS

Bumpers protect the screw and nut assembly from damage at end of stroke



# Tolomatic ... MAXIMUM DURABILITY

#### RECIRCULATING BALL BEARING SYSTEM



- Unique design incorporates hardened steel raceways integral to the aluminum extrusion
- Bearing surfaces are adjusted at the factory for optimum preload and smooth performance
- Recirculating ball bearing system provides guidance, high efficiency and durability

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#### Prevent contaminants from entering the sealing band area to protect internal components

#### **BELT TENSIONING SYSTEM**

- Full access to the idle pulley allows ease of adjustment for alignment and tensioning
- Dual adjustment screws and field tensioning kit provide simple maintenance



### LOAD-BEARING CARRIER DESIGN

Load and moments are transmitted directly to the actuator body



**OPTIONS** 





### •AUXILIARY CARRIER doubles the load capacity and increases pitch and yaw bending moment

- and increases pitch and yaw bending moment capacities
- **DUAL 180° CARRIER** doubles the load capacity, increases roll and yaw bending moment capacities and offers a wide mounting platform

### MOUNTING OPTIONS

• SURFACE MOUNT two t-slots are integral on the entire underside of the actuator body for direct mounting

- **TUBE SUPPORTS** provide intermediate support of the actuator body throughout long stroke lengths
- **MOUNTING PLATES** provide intermediate support of the actuator body throughout long stroke lengths

### METRIC OPTION

Provides metric tapped holes for mounting of load to carrier and of actuator to mating surfaces

#### •SWITCHES

Styles include: reed, hall-effect or triac. Select either 5 m potted cable with flying leads or 150 mm to quickdisconnect coupler with mating 5 m cable



#### YOU CAN CHOOSE:

- Polyurethane steel-cord reinforced HTD style belt (standard)
- Polyurethane Kevlar reinforced HTD style belt



### **SPECIFICATIONS both Screw & Belt Drive**

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### **DYNAMIC BENDING MOMENTS AND LOADS**

				METRIC		U.S. (	ONVENTIO	onal
SINGLE (STANDARD) CARRIER		Size	10	15	20	10	15	20
Fz 1	Mx Moment (Roll)	(N-m : Ib-in)	28.2	97	188	250	859	1,662
Fy Mz	My Moment (Pitch)	(N-m : Ib-in)	30.4	117	166	269	1,033	1,472
My	Mz Moment (Yaw)	(N-m : Ib-in)	17.6	67	96	156	596	850
Mx Z	Fy Load (Radial)	(N : Ib)	1,517	3,737	5,155	341	840	1,159
	Fz Load (Lateral)	(N : Ib)	2,629	6,468	8,932	591	1454	2008
AUXILIARY CARRIER: Increases rigidity, load-ca	rrying capacity and m	oments Size	10	15	20	10	15	20
Fz 1	Mx Moment (Roll)	*(N-m : lb-in)	57	194	376	500	1,718	3,324
Fy Mz	My Moment (Pitch)	*(N-m : lb-in)	319	1,326	1,838	2,825	11,734	16,265
My	Mz Moment (Yaw)	*(N-m : lb-in)	184	766	1,061	1,630	6,779	9,388
Mx	Fy Load (Radial)	(N : Ib)	3,034	7,473	10,311	682	1,680	2,318
"D"	Fz Load (Lateral)	(N : Ib)	5,258	12,935	17,864	1,182	2,908	4,016
	Minimum Dimension	<b>n 'D'</b> (mm : in)	124	205	206	4.88	8.07	8.10
DUAL 180° CARRIER: Allows 90° rotation of load	, adds load bearing su	rface Size	10	15	20	10	15	20
Fz	Mx Moment (Roll)	(N-m : Ib-in)	74	279	512	657	2,468	4,527
Fy	My Moment (Pitch)	(N-m : lb-in)	35.3	135	192	312	1,192	1,700
My	Mz Moment (Yaw)	(N-m : Ib-in)	61	233	333	538	2,066	2,944
Mx Z	Fy Load (Radial)	(N : Ib)	5,258	12,935	17,864	1,182	2,908	4,016
	Fz Load (Lateral)	(N : lb)	3,034	7,473	10,311	682	1,680	2,318
AUXILIARY DUAL 180° CARRIER: Substantially in	ncreases moment and	loads Size	10	15	20	10	15	20
Fz 1	Mx Moment (Roll)	* (N-m : lb-in)	149	558	1,023	1,314	4,936	9,054
Fy Mz	My Moment (Pitch)	* (N-m : lb-in)	376	1,532	2,121	3,328	13,558	18,776
	Mz Moment (Yaw)	* (N-m : lb-in)	652	2,652	3,675	5,768	23,468	32,530
	Fy Load (Radial)	(N : Ib)	10,516	25,871	35,728	2,364	5,816	8,032
	Fz Load (Lateral)	(N : lb)	6,067	14,946	20,622	1,364	3,360	4,636
	Minimum Dimensio	<b>n 'D'</b> (mm : in)	124	205	206	4.88	8.07	8.10

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The Dual 180° carrier requires its own proprietary tube supports and foot mounts. See dimensional information. Breakaway torque will also increase when using the Auxiliary carrier or the Dual 180° carrier options. When ordering, determine working stroke and enter this value into the configuration string. Overall actuator length will automatically be calculated.

Deflection Considerations: In applications where substantial Mx or My moments come into play, deflection of the cylinder tube, carrier and supports must be considered. The deflection factors shown in the Load Deflection charts on the following page are based on cylinder mounted with tube supports at minimum recommended spacing. If more rigidity is desired, refer to the Auxiliary or Dual Carrier options.

\*Loads shown in table are at minimum "D" dimension, for ratings with longer "D" dimension see graphs on page B3\_10.

Life of the actuator will vary for each application depending on the combined loads, motion parameters and operating conditions. The load factor (L<sub>F</sub>) ratios for each application must not exceed a value of 1.5 (see formula at right). Exceeding a load factor of 1.5 will diminish the actuator's rated life.  $L_F = \frac{Mx}{Mx_{max}} + \frac{My}{My_{max}} + \frac{Mz}{Mz_{max}} + \frac{Fy}{Fy_{max}} + \frac{Fz}{Fz_{max}} \le 1.5$ 

With combined loads,  $L_F$  must not exceed the value 1.5

Tolomatic EXCELLENCE IN MOTION

### **B3S & B3W Electric Rodless Actuators**

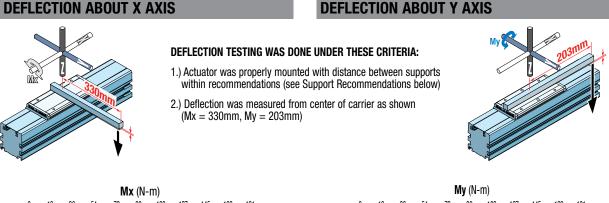
### **SPECIFICATIONS both Screw & Belt Drive**

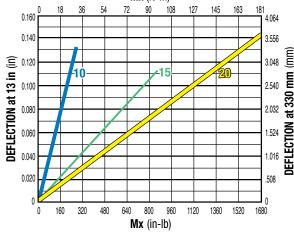
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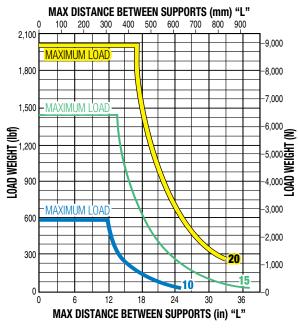
#### LOAD DEFLECTION

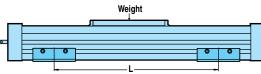
#### **DEFLECTION ABOUT X AXIS**



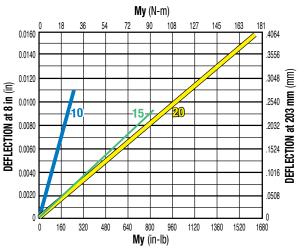


### SUPPORT RECOMMENDATIONS

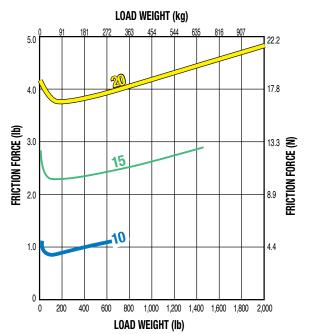




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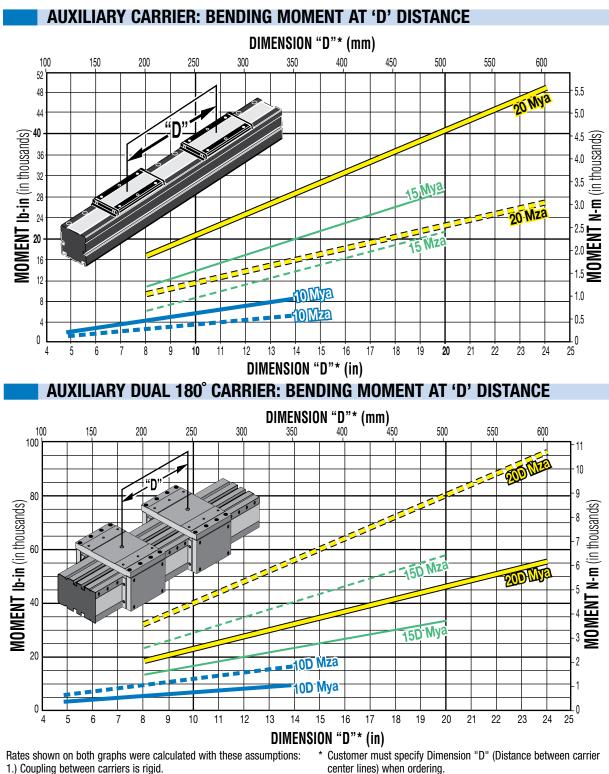
### **FRICTION FORCE**



### **B3S & B3W Electric Rodless Actuators**

### **SPECIFICATIONS both Screw & Belt Drive**

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2.) Load is equally distributed between carriers.

3.) Coupling device applies no misalignment loads to carriers.

center lines) when ordering.

Life of the actuator will vary for each application depending on the combined loads, motion parameters and operating With combined conditions. The load factor (L<sub>r</sub>) ratios for each application must not loads, L, must not  $\frac{Mx}{Mx_{max}} + \frac{My}{My_{max}} + \frac{Mz}{Mz_{max}} + \frac{Fy}{Fy_{max}} + \frac{Fz}{Fz_{max}} \le 1.5$ exceed a value of 1.5 (see formula at right). Exceeding a load exceed the value factor of 1.5 will diminish the actuator's rated life. 1.5

B3S



### **SPECIFICATIONS** Related to Actuator Size and Screw Selection

	METRIC LEAD SCREWS										
	SCREW		LEAD	LEAD		MAX	MAX	INE	RTIA (kg-m² x	10 <sup>-6</sup> )	BREAKAWAY
	DIA.	SCREW	(mm/		BACKLASH			BASE A	CTUATOR	PER/mm OF	TORQUE
	(mm)	TYPE	turn)	(mm/300)	(mm)	(N)	(mm)	In Line	<b>Rev. Parallel</b>	STROKE	(N-m)
B3S10	10	BNM	10	0.10	0.06	1,832	1,630	1.14	1.43	0.176	0.13
00010	12	SN	12.0	0.13	0.18	800	3,459	3.03	4.50	0.410	0.20
B3S15	15	SN	12.0	0.13	0.18	900	3,388	11.35	12.96	0.966	0.27
00010	16	BN(L)	5.0	0.13	0.38	7,300	3,388	11.93	14.04	1.258	0.16
B3S20	20	BN(L)	5.0	0.13	0.38	11,700	3,337	36.97	39.28	3.102	0.25

(L) for low backlash ball screws: backlash = 0.05 mm

#### INCH (US Conventional) LEAD SCREWS

	SCREW			LEAD		MAX	MAX	I	NERTIA (lb-in²)		BREAKAWAY
	DIA.	SCREW	TPI	ACCURACY	BACKLASH	THRUST*	STROKE	BASE A	CTUATOR	PER/in OF	TORQUE
_	(in)	TYPE	(turns/in)	(in/ft)	(in)	(lbf)	(in)	In Line	<b>Rev. Parallel</b>	STROKE	(lb-in)
	0.375	BN(L)	08	0.004	0.015	130	64.2	0.0034	0.0042	0.0005	1.125
	0.500	SN	05	0.006	0.007	170	136.2	0.0114	0.0142	0.0017	1.250
B3S10	0.500	SN	02	0.005	0.007	170	134.2	0.0159	0.0187	0.0017	1.750
	0.500	SNA	02	0.005	0.003	170	134.2	0.0193	0.0221	0.0017	1.750
	0.500	SN	01	0.006	0.007	170	100.2	0.0320	0.0348	0.0017	2.500
	0.500	BN(L)	02	0.003	0.015	800	61.4	0.0253	0.0282	0.0017	1.563
	0.625	BN(L)	05	0.003	0.015	800	61.4	0.0397	0.0467	0.0042	1.250
B3S15	0.625	SN	02	0.005	0.007	200	133.4	0.0480	0.0550	0.0042	1.875
	0.625	SNA	02	0.005	0.003	200	133.4	0.0480	0.0550	0.0042	1.875
	0.750	SN	01	0.005	0.007	300	133.4	0.1185	0.1329	0.0087	2.813
B3S20	0.750	BN(L)	02	0.004	0.015	2,700	131.4	0.1159	0.1224	0.0087	3.125
03320	0.750	BN(L)	05	0.003	0.015	950	131.4	0.1045	0.1110	0.0087	2.188

(L) for low backlash ball screws: backlash = 0.0020"

#### SCREW CODE DESCRIPTION

- SN Solid Nut
- SNA Anti-backlash Solid Nut
- BN Ball Nut
- BNL Low-Backlash Ball Nut

#### Contact Tolomatic for higher accuracy and lower backlash options.

\* For Acme screws, maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.

For ball screws, maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.



### **SPECIFICATIONS**

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					METRIC		
		WEI	GHT	WEIGHT PER	<sup>1</sup> STRAIGHTNESS &	<sup>2</sup> TEMPERATURE	
		CARRIER	BASE	UNIT OF STROKE		RANGE	
		(kg)	(kg)	(g/mm)	(mm)	(°C)	<sup>3</sup> IP RATING
ſ	B3S10	0.40	1.00	5.40			
	B3S15	0.70	3.96	10.18	0.00067 x L*	4 - 54	44
	B3S20	0.97	6.52	15.73			

	WEI	GHT	WEIGHT PER
	CARRIER	BASE	UNIT OF STROKE
	(kg)	(kg)	(g/mm)
B3S10D	1.05	2.31	7.32
B3S15D	2.93	6.53	12.14
B3S20D	4.83	13.36	23.30

<sup>1</sup>The listed values relating to straightness/flatness are intended for reference purposes only, and not as an engineering standard of absolute tolerance for a given actuator. Appropriate installation is the single most important factor in reducing such deviation, so good engineering practices such as measurement, mapping, etc. must be employed in applications with stringent straightness/flatness requirements.

accurate actuator selection

<sup>2</sup> Heat generated by the motor and drive should be taken into consideration as well as linear velocity and work cycle time. For applications that require operation outside of the recommended temperature range, contact the factory.

			INCH (L	JS Conventional)		
	WEI	GHT	WEIGHT PER	<sup>1</sup> STRAIGHTNESS &	<sup>2</sup> TEMPERATURE	
	CARRIER	BASE	UNIT OF STROKE		RANGE	
	(lbs)	(lbs)	(lbs/in)	(in)	(°F)	<sup>3</sup> IP RATING
B3S10	0.85	2.15	0.30			
B3S15	1.56	8.75	0.57	0.00067 x L*	40 - 130	44
B3S20	2.15	14.38	0.88			

	WE	GHT	WEIGHT PER
	CARRIER	BASE	UNIT OF STROKE
	(lbs)	(lbs)	(lbs/in)
B3S10D	2.32	5.10	0.41
B3S15D	6.47	14.40	0.68
B3S20D	10.65	29.45	1.31

<sup>3</sup> Protected against ingress of solid particles greater than .039 in (1mm) and splashing water.

\* "L" is maximum distance between supports- See the support recommendation graph on page B3\_9.

LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported, if subjected to continuous rapid reversing duty and/or under dynamic conditions.

### LEAD SCREW EFFICIENCY

SCREW/NUT		SIZE	
STYLE	10	15	20
Composite (ACME)		0.60	
Ball		0.90	
Ball Low Backlash		0.85	

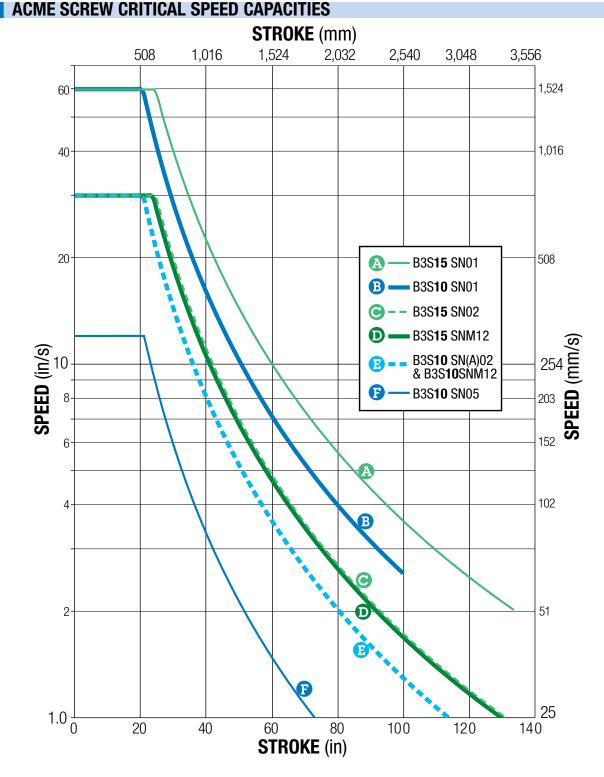


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### **ACME SCREW/NUT COMBINATIONS**

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Dotted lines represent maximum stroke for screw selections.

 SCREW CODE
 DESCRIPTION

 SNM
 Solid Nut

 SNA
 Anti-backlash Solid Nut

For Screw PV limits, refer to the individual charts located in the technical section for each actuator body size.

B3S

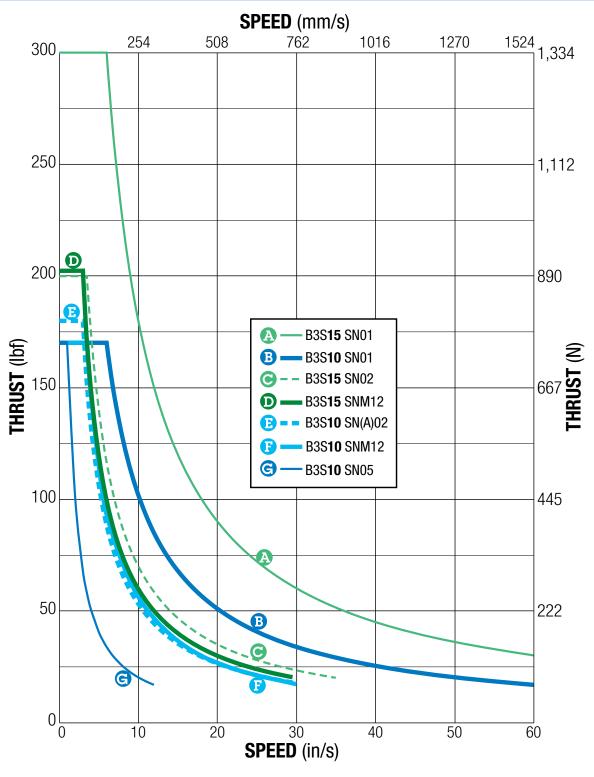




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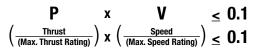
#### **ACME SCREW PV LIMITS**



🛕 \* Maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity Limitation.

PV LIMITS: Any material which carries a sliding load is limited by heat buildup. The factors that affect heat generation rate in an application are the pressure on the nut in pounds per square inch and the surface velocity in feet per minute. The product of these factors provides a measure of the severity of an application.

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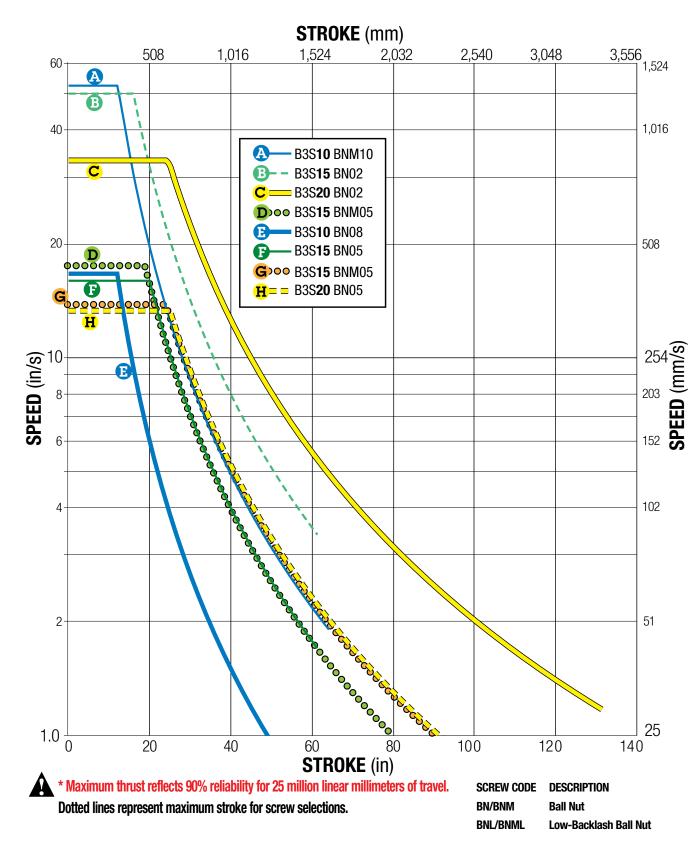
### **BALL SCREW/NUT COMBINATIONS**

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### **BALL SCREW CRITICAL SPEED CAPACITIES**

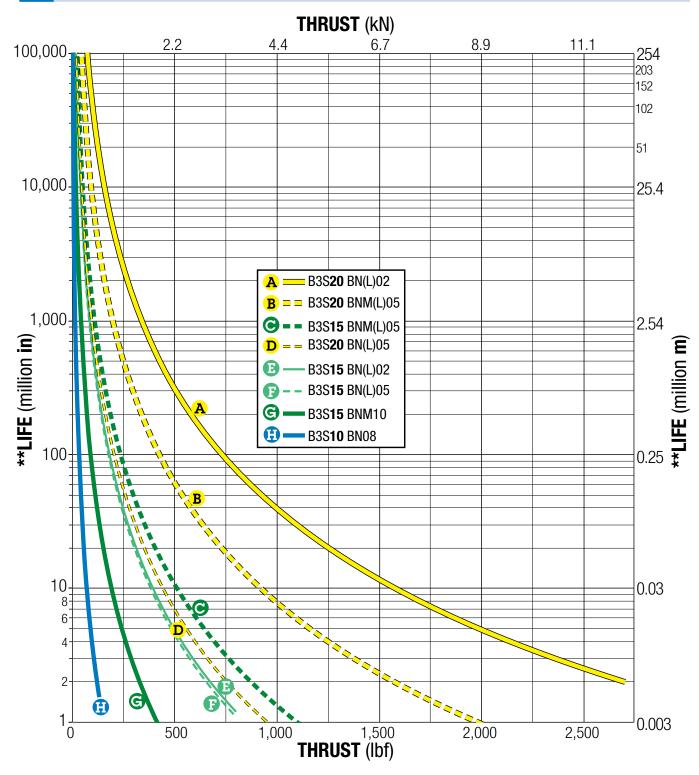


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### **BALL SCREW/NUT COMBINATIONS**

**BALL SCREW LIFE CAPACITIES** 



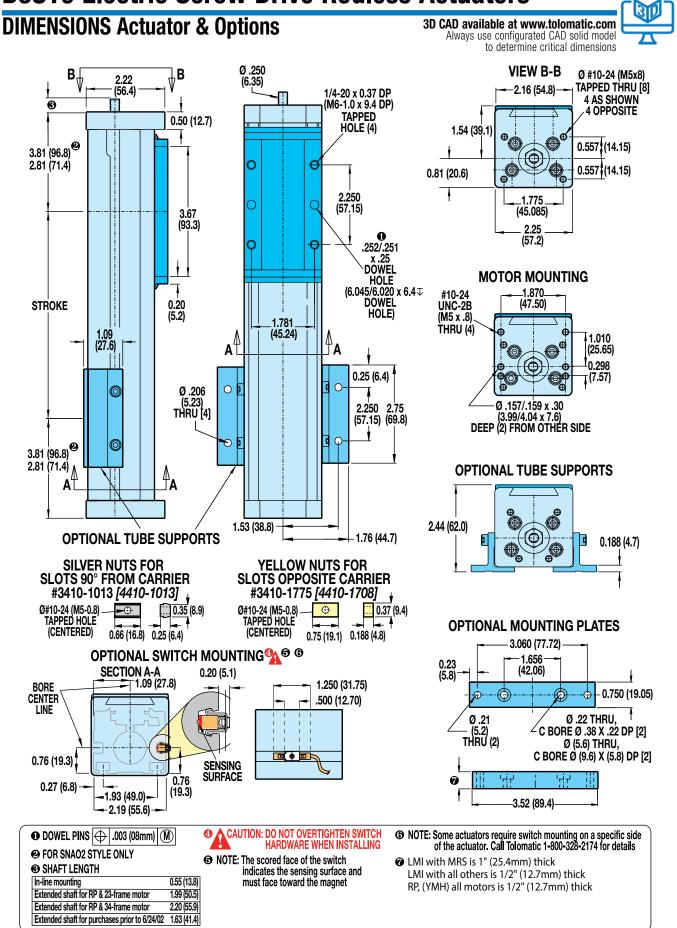
\* Maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.

Dotted lines represent maximum thrust for screw selections.

\*\*Life indicates theoretical maximum life of screw only, under ideal conditions and does not indicate expected life of actuator.

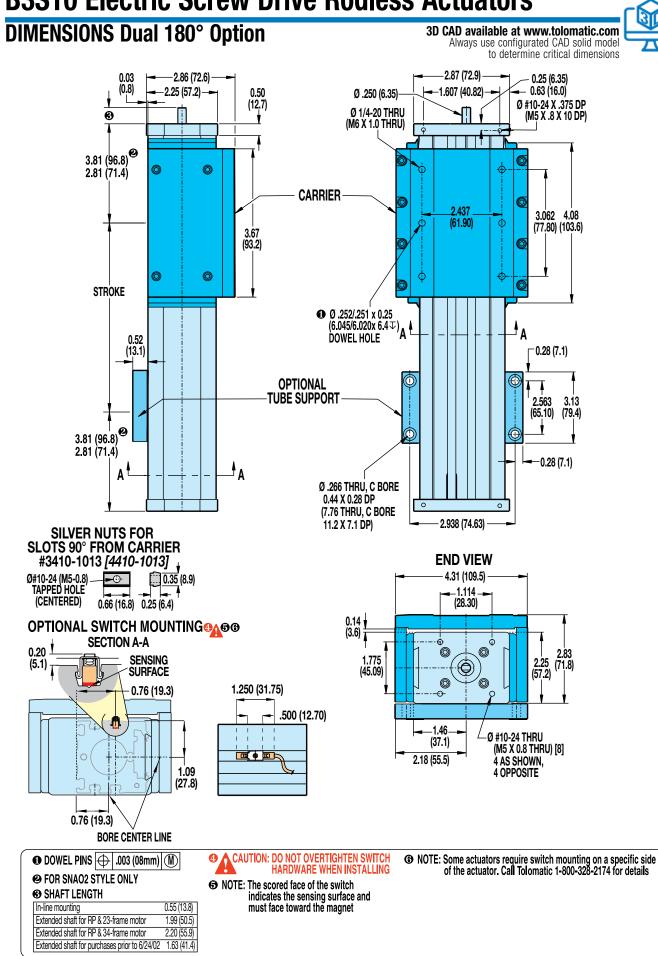
B3S





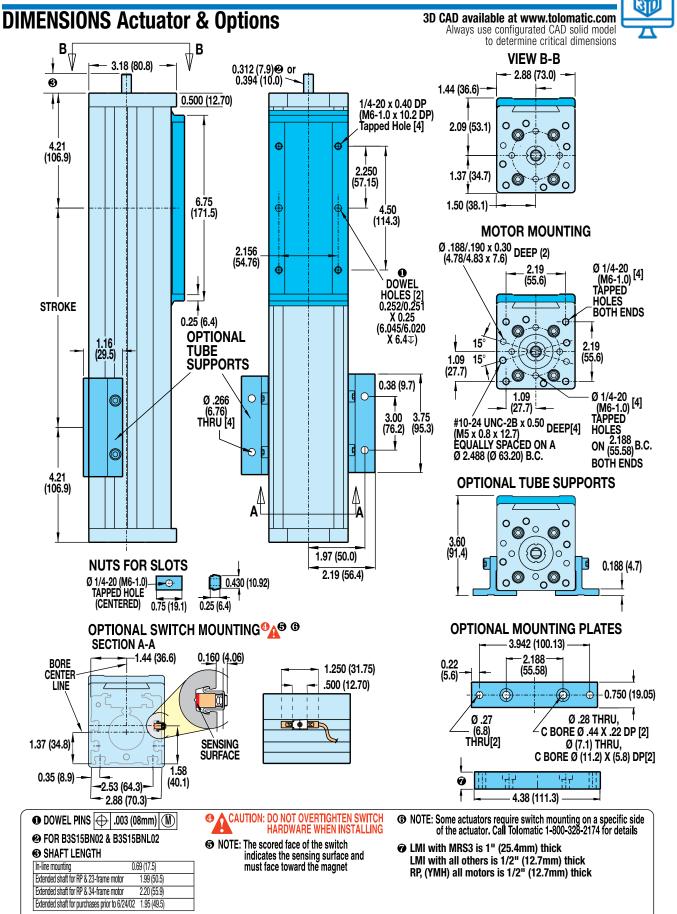
Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)





B3S



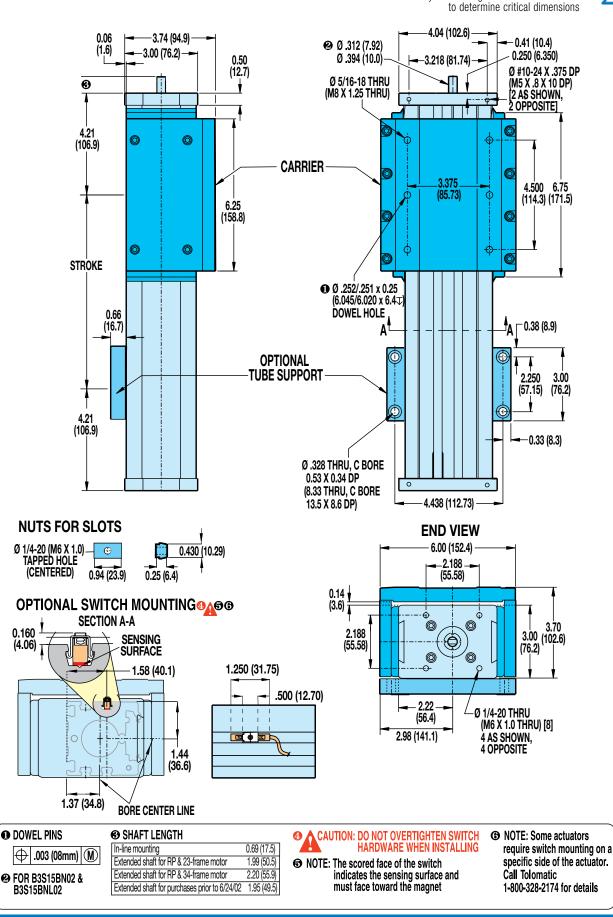


Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)



### DIMENSIONS Dual 180° Option

3D CAD available at www.tolomatic.com Always use configurated CAD solid model



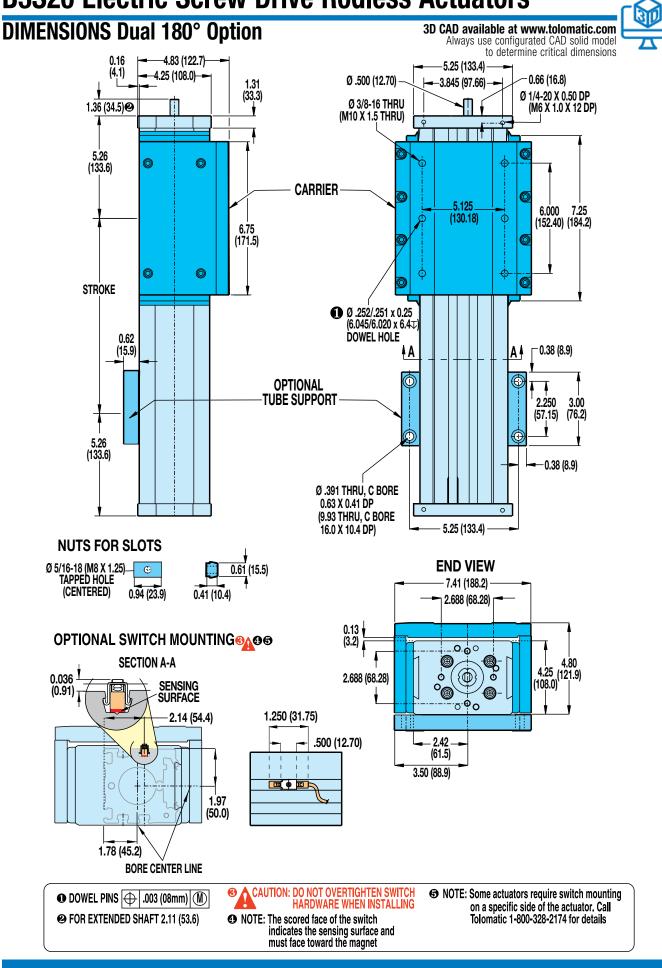


#### **DIMENSIONS Actuator & Options** 3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions ∯₿ В 4.20 VIEW B-B $\mathbf{A}$ (106.6)4.25 (107.9)-Ø 0.50 (12.7) 3.84 (92.5) 1.36 (34.5) 5/16 - 18 x 0.56 DP 1.31 (33.2) (M8-1.25 x 14.2 DP) Tapped Hole [4] 2.66 (67.5) 0 0 0 5.26 Ð Ð 0 -0 o (133.6)0 1.78 (45.2) ۲ ¢.∕® 2.375 (60.33) 7.25 2.13 (54.1) $\oplus$ 4.750 (184.1) 1.563 (120.65) (39.65) MOTOR MOUNTING 3.125 Ø .188/.190 x 0.30 (4.78/4.83 x 7.6) DEEP [2] (79.30)Ø 1/4-20 (M6-1.0) [4] TAPPED φ ф 0 DOWEL 2.688 (68.28 HOLES [2] 0.252/0.25 HOLES BOTH ENDS STROKE X 0.25 0.25 (6.35) [2] (6.045/6.020 -0 0 0 X 6.4**↓**) 1.50 (38.1) 15° (**Ð**) 2.688 (68.28) 15° ⊕ œ -ò 0.31 (7.9) 0 0 Ø.328 0 #10-24 UNC-28 x 0.50 DEEP [4] (8.33) THRU [4] 3.375 4.00 (85.73) (101.6) (M5 x 0.8 x 12.7) EQUALLY SPACED ON A Ø 3.010 (Ø 76.45) B.C. e Œ Θ 6 5.26 **OPTIONAL TUBE SUPPORTS** (133.6) A Д 0 0 0 0 0 4.53 (115.1) 0 0 $(\mathbf{O})$ 2.56 (65.0) **OPTIONAL TUBE SUPPORTS** 0 Þ 0 đ 0.188 (4.7) 0 2.84 (72.1) O 0 O NUTS Ø 5/16 - 18 (M8-1.25)-FOR TAPPED HOLE 0.61 (15.5) **-** $\bigcirc$ · FOR (CENTERED) 0.94 (23.8) 0.41(10.4) SLOTS OPTIONAL MOUNTING PLATES OPTIONAL SWITCH MOUNTING 6 0 5.125 (130.18) **SECTION A-A** 2.938 1.97 (50.0) 0.036 (0.91) 0.28 BORE (74.63)1.250 (31.75) (7.1) CENTER .500 (12.70) LINE $\odot$ 0.750 (19.05) $(\Phi)$ -fə æ Ø .34 THRU, Ø.33 - (8.3) THRU (2) ∠C BORE Ø .53 X .34 DP [2] Ø (8.7) THRU, SENSING 1.78 (45.2) C BORE Ø (13.5) X (8.6) DP [2] SURFACE 2.14 (54.4) 0.50 (12.7) 도로 0.50 (12.7)--3.44 (87.3)-5.69 (144.5) -3.94 (100.0<del>)</del> CAUTION: DO NOT OVERTIGHTEN SWITCH ONTE: Some actuators require switch mounting on a specific side of the actuator. Call Tolomatic 1-800-328-2174 for details 8 ● DOWEL PINS | ↔ | .003 (08mm) | ① HARDWARE WHEN INSTALLING FOR EXTENDED SHAFT 2.11 (53.6) ONOTE: The scored face of the switch indicates the sensing surface and must face toward the magnet

вз 21

Tolomatic

B3S



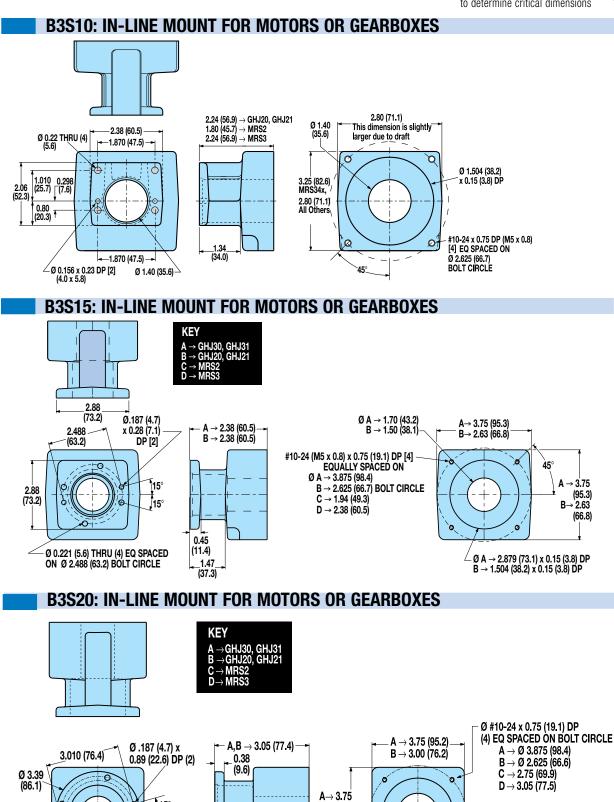
B3 22

**Tolomatic** 

**DIMENSIONS Actuator & Options** 

3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions







15°

**1**15°

Ø .221 (5.6) THRU (4)

Ø 3.010 (76.4) BOLT CIRCLE

EQ SPACED ON

1.56

(39.6)

 $\begin{array}{c} \textbf{(95.2)}\\ \textbf{B}{\rightarrow} \textbf{ 3.00} \end{array}$ 

(76.2)

45

 $\textbf{A} \rightarrow \textbf{\emptyset}$  2.25 (57.2)

 $B \rightarrow Ø 1.50 (38.1)$ 

→ Ø 2.879 (73.1)

x 0.15 (3.81) DP

x 0.15 (3.81) DP

B→Ø 1.504 (38.2)

ø

#### DIMENSIONS Reverse Parallel Mounting 3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions **STANDARD CARRIER REVERSE-PARALLEL REVERSE-PARALLEL REVERSE-PARALLEL REVERSE-PARALLEL BOTTOM (RPB)** TOP (RPT)\* LEFT (RPL) **RIGHT (RPR)** mounting surface shown up mounting surface shown up mounting surface shown up mounting surface shown up TOP MOUNT SIDE MOUNT (Right Shown) **BOTTOM MOUNT** A В F٦ E H∓ G -C-**DUAL 180° CARRIER REVERSE-PARALLEL REVERSE-PARALLEL REVERSE-PARALLEL** REVERSE-PARALLEL **BOTTOM (RPB)** TOP (RPT)\* LEFT (RPL) **RIGHT (RPR)** mounting surface shown up mounting surface shown up mounting surface shown up mounting surface shown up

**Reduction Drive Weight** 

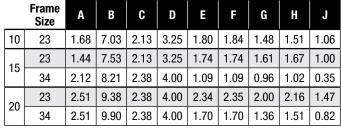
	kg	lb
1:1 & 2:1 Ratio	0.93	2.06
1:1 Ratio	0.98	2.17
2:1 Ratio	1.09	2.40
1:1 Ratio	1.39	3.07
2:1 Ratio	1.47	3.23
1:1 Ratio	1.42	3.13
2:1 Ratio	1.49	3.29
	2:1 Ratio 1:1 Ratio 2:1 Ratio 1:1 Ratio 2:1 Ratio 1:1 Ratio	1:1 &         0.93           2:1 Ratio         0.98           1:1 Ratio         0.98           2:1 Ratio         1.09           1:1 Ratio         1.39           2:1 Ratio         1.47           1:1 Ratio         1.42

<b>Reduction Inertia at Motor Shaft</b>						
		kg-cm <sup>2</sup>	lb-in <sup>2</sup>			
10	1:1 Ratio	0.2559	0.0875			
10	2:1 Ratio	0.3291	0.1125			
15	1:1 Ratio	0.2043	0.0700			
15	2:1 Ratio	0.2767	0.0950			
20	1:1 Ratio	0.3447	0.1180			
20	2:1 Ratio	0.2928	0.1000			

**Reduction Efficiency: 0.95** 

	Frame Size	A	В	C	D	E	F	G	H	J
10	23	42.6	178.6	54.0	82.6	45.6	46.8	37.6	38.4	26.9
15	23	36.6	191.3	54.0	82.6	44.1	44.1	40.8	42.3	25.3
15	34	53.8	208.6	60.3	101.6	27.7	27.7	24.4	25.9	8.9
20	23	63.8	238.4	60.3	101.6	59.5	59.6	50.8	54.7	37.2
20	34	63.8	251.5	60.3	101.6	43.2	43.2	34.4	38.4	20.9

Dimensions in millimeters



Dimensions in inches

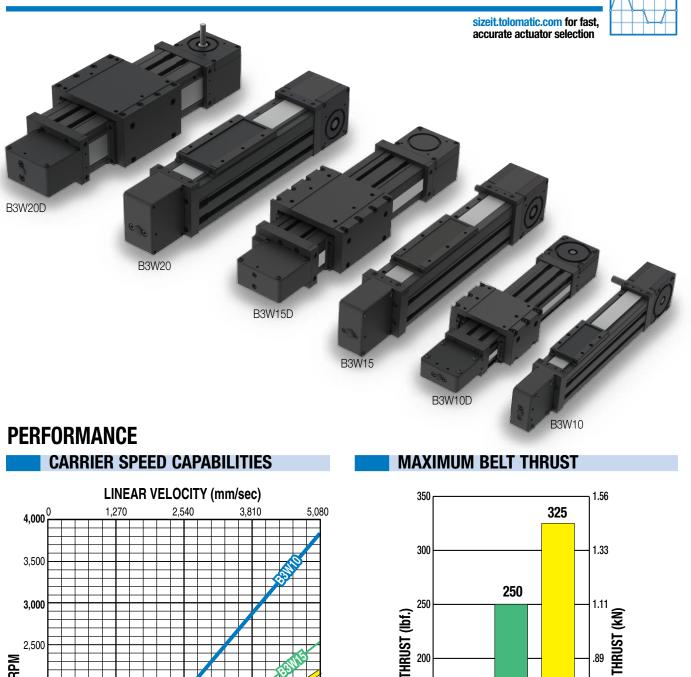


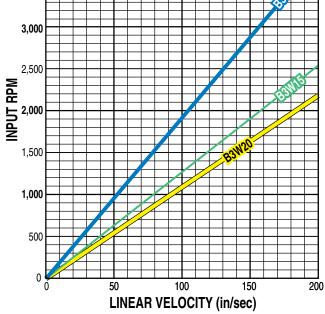
B3S

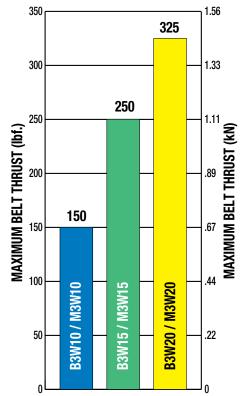
### B3W

\* NOTE: RPT is generally not recommended because the load may interfere with the motor. Stops or spacers may be required.

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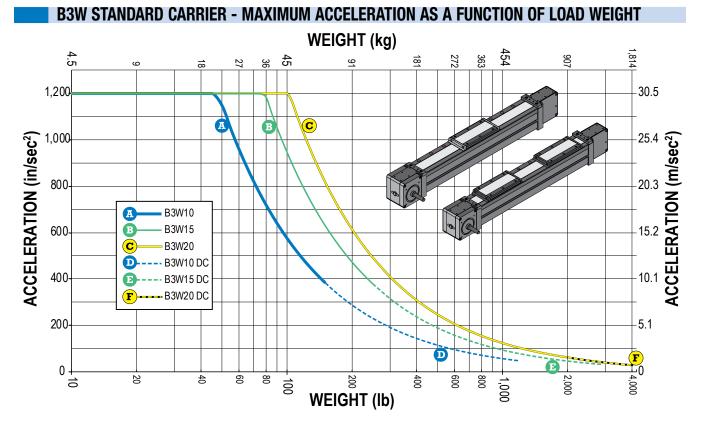
B3S

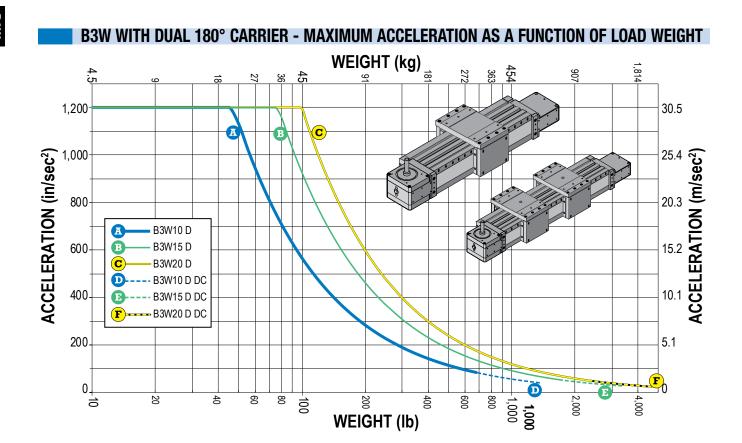
B3W



### PERFORMANCE

sizeit.tolomatic.com for fast, accurate actuator selection







### **SPECIFICATIONS**

sizeit.tolomatic.com for fast, accurate actuator selection

			N	INCH (U.S. Conventional)					
			B3W10	B3W15	B3W20		B3W10	B3W15	B3W20
	Max. Stroke	mm	14,579	10,566	8,128	in	574	416	320
	Max. Velocity	m/sec	5.08	5.08	5.08	in/sec	200	200	200
	Max. Acceleration	m/sec <sup>2</sup>	30.48	30.48	30.48	in/sec <sup>2</sup>	1,200	1,200	1,200
	Max. Input Torque	N-m	8.5	21.2	32.2	lb-in	75.2	188.0	285.0
	Standard (single) Carrier	N-m	1.06	1.41	3.18	lb-in	9.38	12.5	28.13
Break- away Torono	Dual 180° or Aux. Carrier	N-m	1.34	1.69	3.53	lb-in	11.88	15	31.25
<b>∞</b> ~ ⊢	Dual 180 & Aux Carrier	N-m	1.91	2.82	5.37	lb-in	16.88	25	47.5
	Pulley Pitch Dia.	mm	25.48	38.2	44.55	in	1.003	1.504	1.754
	Stroke per Rev.	mm/rev	80.04	120.02	139.95	in/rev	3.151	4.725	5.51
	Repeatability	mm	+/- 0.05	+/- 0.05	+/- 0.05	in	+/- 0.002	+/- 0.002	+/- 0.002
	Straightness & Flatness <sup>1</sup>	mm	0.017 x L*	0.017 x L*	0.017 x L*	in	0.00067 x L*	0.00067 x L*	0.00067 x L*
	Temp. Range <sup>2</sup>	°C	4 - 54	4 - 54	4 - 54	°F	40 - 130	40 - 130	40 - 130
	IP Rating <sup>3</sup>	IP	44	44	44	IP	44	44	44
	Inertia (zero stroke)	kg-cm <sup>2</sup>	0.833	4.073	7.786	lb-in <sup>2</sup>	0.2846	1.3917	2.6607
	Inertia (per unit of stroke)	kg-cm²/mm	0.00018	0.0002	0.00131	lb-in²/in	0.0016	0.0017	0.0114
	Inertia of pulley	kg-cm <sup>2</sup>	0.027	0.219	0.422	lb-in <sup>2</sup>	0.0093	0.0748	0.1441
	Inertia of carrier	kg-cm <sup>2</sup>	0.305	1.489	2.847	lb-in <sup>2</sup>	0.1041	0.5089	0.9728
	Weight of pulley	kg	0.0068	0.0244	0.047	lb	0.015	0.054	0.1036
	Weight of carrier	kg	0.39	0.71	0.97	lb	0.85	1.56	2.14
	Weight (zero stroke)	kg	3.42	11.39	16.06	lb	7.54	25.12	35.4
	Weight (per unit of stroke)	kg/mm	0.0069	0.0071	0.0128	lb/in	0.389	0.395	0.716

		B3W10D	B3W15D	B3W20D		B3W10D	B3W15D	B3W20D
Weight of carrier	kg	1.09	3.02	4.86	lb	2.40	6.66	10.72
Weight (zero stroke)	kg	4.36	13.71	19.94	lb	9.62	30.22	43.97
Weight (per unit of stroke)	g/mm	8.93	13.57	22.14	lb/in	0.50	0.76	1.24



<sup>1</sup> The listed values relating to straightness/flatness are intended for reference purposes only, and not as an engineering standard of absolute tolerance for a given actuator. Appropriate installation is the single most important factor in reducing such deviation, so good engineering practices such as measurement, mapping, etc. must be employed in applications with stringent straightness/flatness requirements.

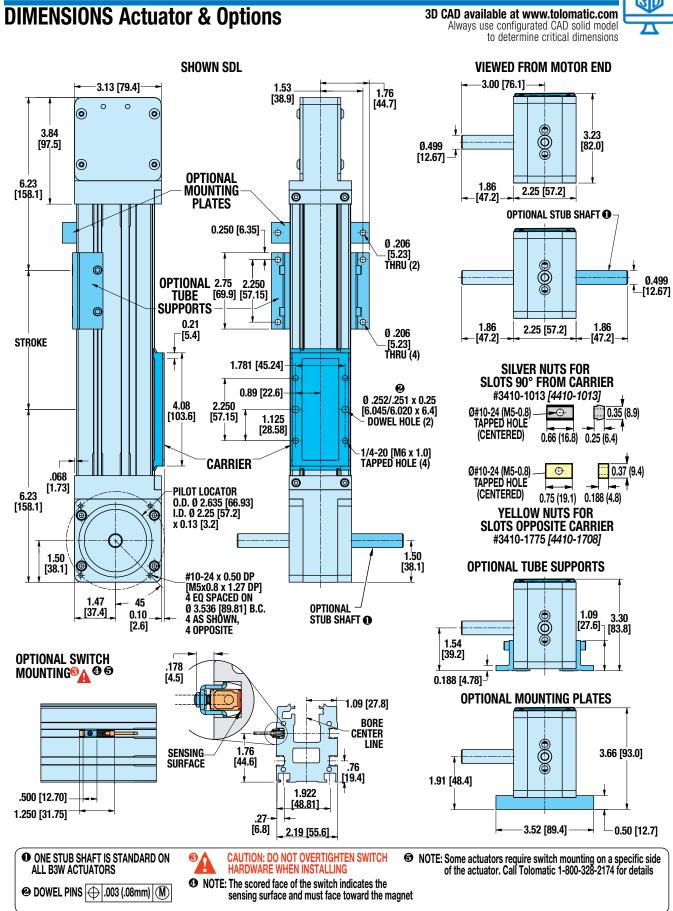
<sup>2</sup> Heat generated by the motor and drive should be taken into consideration as well as linear velocity and work cycle time. For applications that require operation outside of the recommended temperature range, contact the factory. <sup>3</sup> Protected against ingress of solid particles greater than 1 mm (.039 in) and splashing water. \*"L" is maximum distance between supports - See Support Recommendations graph pg B3\_9.

LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported if subjected to continuous rapid reversing duty and/or under dynamic conditions.

NOTE: Zero stroke inertia and weight are for an assembled actuator (including carrier, pulley and belt material) that has zero stroke length. To calculate system inertia use the formula below:

System Inertia = Inertia (zero stroke) + [Inertia (per unit of stroke) x number of units] (For weight calculation substitute inertia with weight in the above formula)





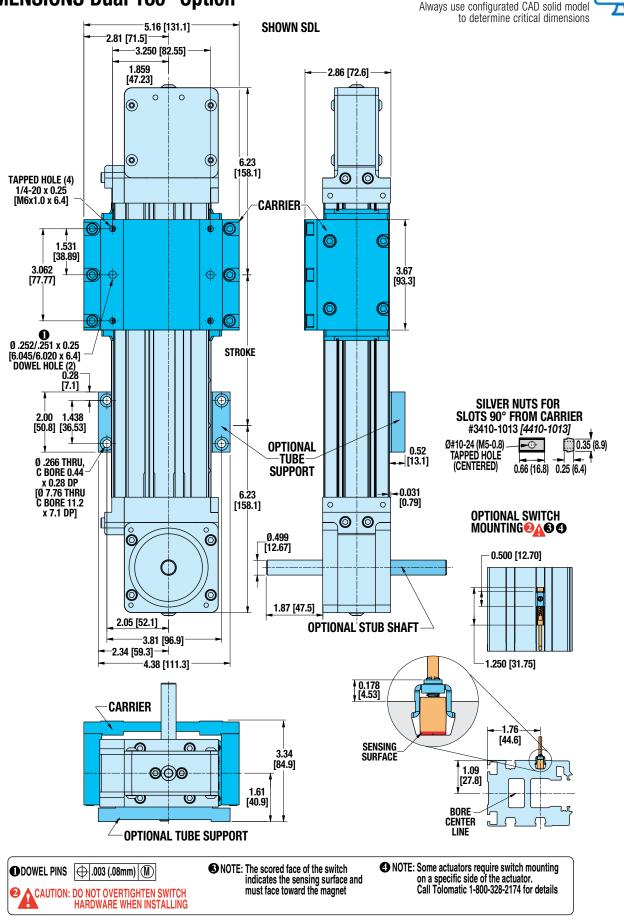
Unless otherwise noted, all dimensions shown are in inches [Dimensions in brackets are in millimeters]



3D CAD available at www.tolomatic.com

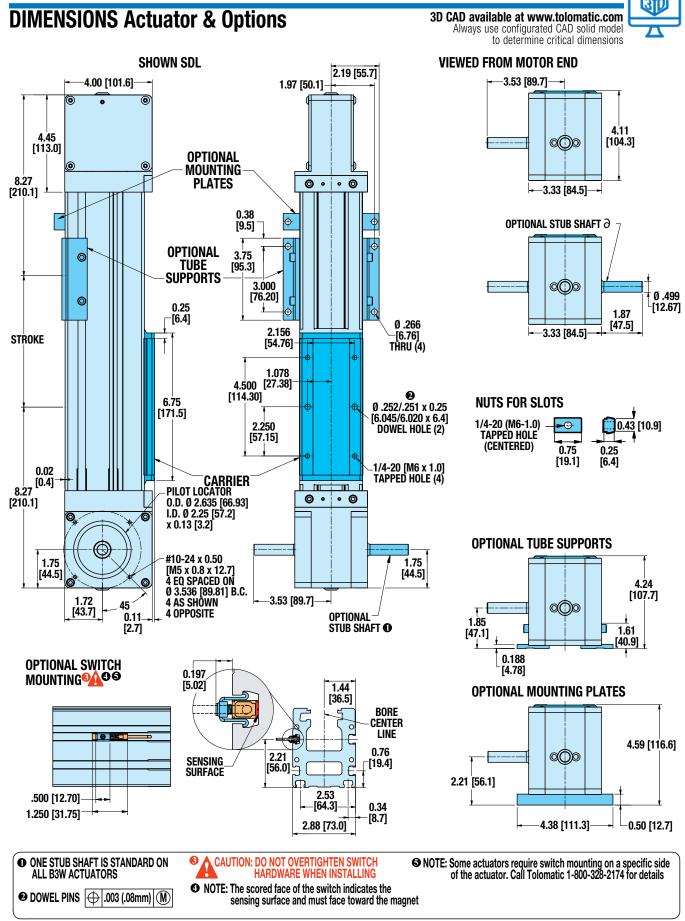
### **DIMENSIONS Dual 180° Option**

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вз 29

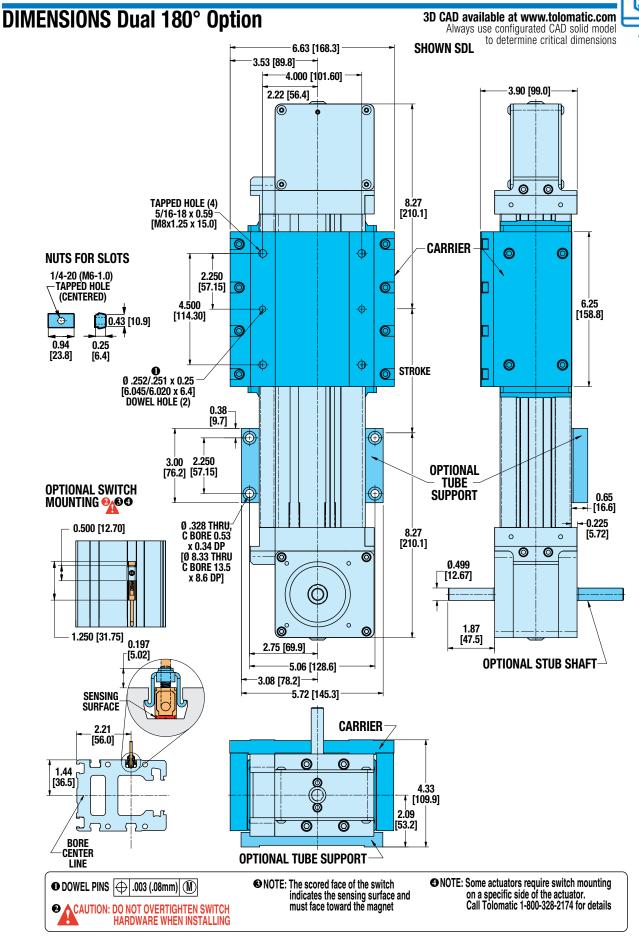
B3W



Unless otherwise noted, all dimensions shown are in inches [Dimensions in brackets are in millimeters]



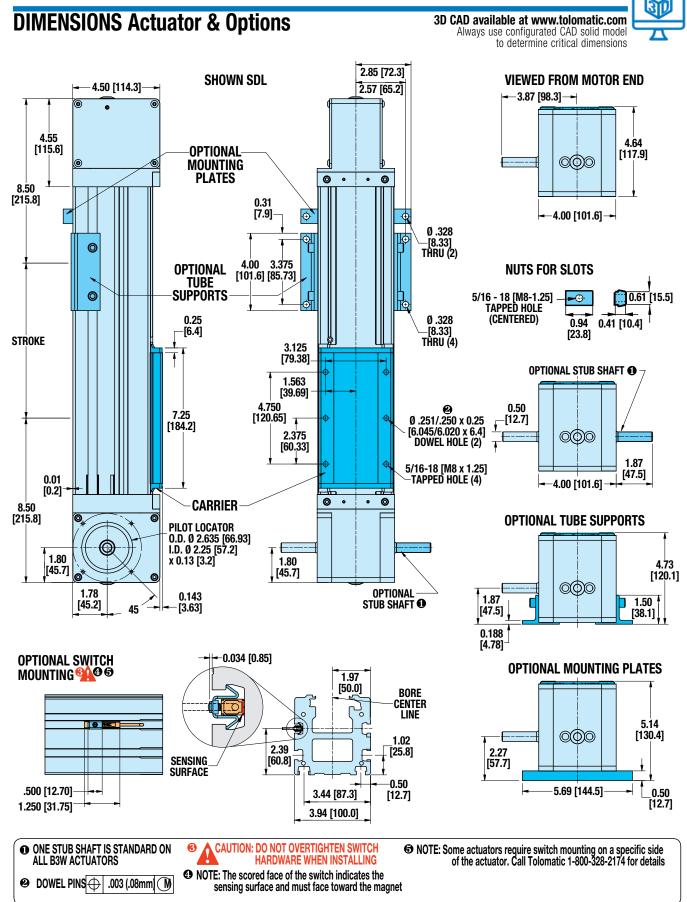
B3W



вз 31

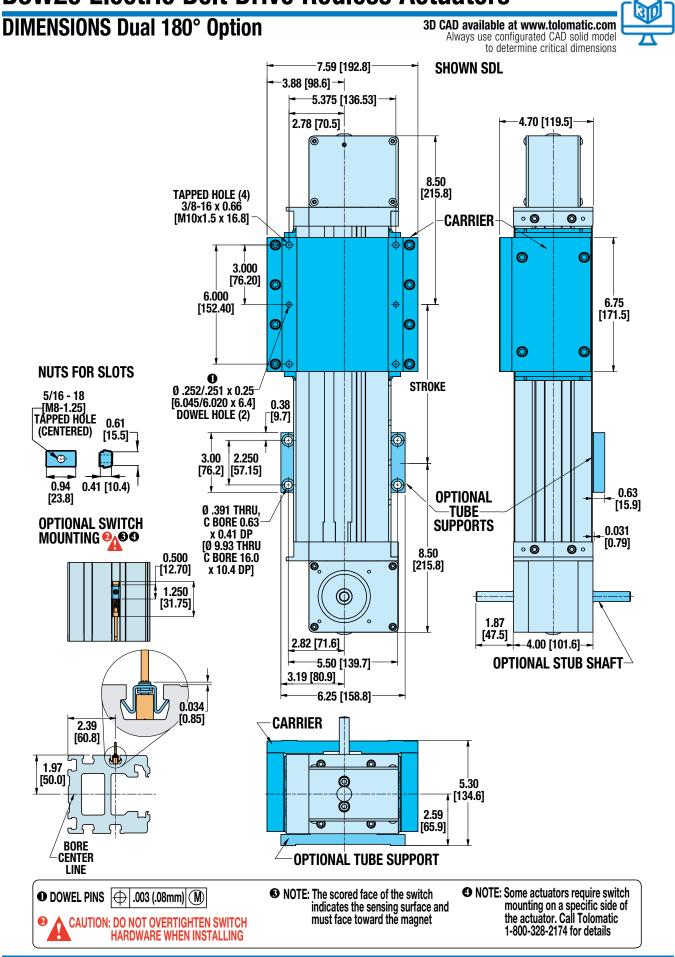
Tolomatic

83



Unless otherwise noted, all dimensions shown are in inches [Dimensions in brackets are in millimeters]





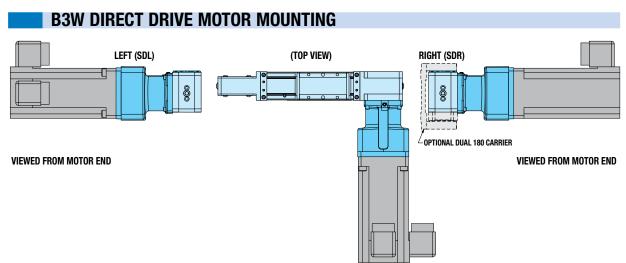
вз 33

**Tolomatic** 

### MOTOR MOUNTING

**3D CAD available at www.tolomatic.com** Always use configurated CAD solid model to determine critical dimensions





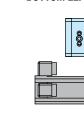
### B3W(D) REDUCTION DRIVE MOTOR MOUNTING

### STANDARD CARRIER



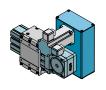
TOP LEFT (SDTL)\*

BOTTOM LEFT (SDBL)

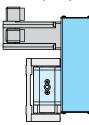




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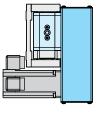
TOP LEFT (SDTL)



**Tolomatic** 



BOTTOM LEFT (SDBL)





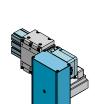
8

TOP RIGHT (SDTR)\*

TOP RIGHT (SDTR)

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вз 34



BOTTOM RIGHT (SDBR)

**BOTTOM RIGHT (SDBR)** 

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### **B3S & B3W Electric Rodless Actuators**

### **SWITCHES**



There are 10 sensing choices: DC reed, form A (open) or form C (open or closed); AC reed (Triac, open); Hall-effect, sourcing, PNP (open); Hall-effect, sinking, NPN (open); each with either flying leads or QD (quick disconnect). Commonly used to send analog signals to PLC (programmable logic controllers), TLL, CMOS circuit or other controller device. These switches are activated by the actuator's magnet.

Switches contain reverse polarity protection. QD cables are shielded; shield should be terminated at flying lead end.

If necessary to remove factory installed switches, be sure to reinstall on the same of side of actuator with scored face of switch toward internal magnet.

#### **SPECIFICATIONS**

	REED DC			REED AC		HALL-EFFECT DC				
ORDER CODE	RT	RM	BT	BM	CT	CM	ΤT	ΤM	ΚT	КM
LEAD	5m	QD*	5m	QD*	5m	QD*	5m	QD*	5m	QD*
CABLE SHIELDING	Unshielded	Shielded†	Unshielded	Shielded+	Unshielded	Shielded+	Unshielded	Shielded+	Unshielded	Shielded†
SWITCHING LOGIC	"A" Norm	ally Open	"C" Norma <b>ll</b> y (	Open or Closed	Triac Norr	nally Open	PNP (Sourci Op	ng) Norma <b>ll</b> y en	NPN (Sinking)	Norma <b>li</b> y Open
MECHANICAL CONTACTS	Single-Pole S	Sing <b>l</b> e-Throw	Single-Pole [	Double-Throw	Single-Pole	Sing <b>l</b> e-Throw	NO,	These Are Solid	d State Compon	ents
COIL DIRECT	Ye	es	Y	es	Y	es				
POWER LED	None		No	one	Nc	one	None		None	
SIGNAL LED	Red 🔍	TOL-O-MATIC					Red 🔍	TOL-O-MATIC	Red 🖭	rol-o-matic]
OPERATING VOLTAGE	200 Vo	lc max.	120 Vo	dc max.	120 Va	120 Vac max.		5 - 25 Vdc		
OUTPUT RATING		-			-	— 25 Vdc, 200mA dc				
OPERATING TIME	0.6 ms (including)		0.7 msec max. (including bounce)		_		< 10 micro sec.			
OPERATING TEMPERATURE			-40°F [-40°C] 1	to 158°F [70°C]				0°F [-18°C] to 150°F [66°C]		
RELEASE TIME		1.0 ms	ec. max.			_	—			
ON TRIP POINT		-			-	_	150 Gauss maximum			
OFF TRIP POINT		-				_	40 Gauss minimum			
**POWER RATING (WATTS)	10	.0 §	3.0	) § §	1(	).0	5.0			
VOLTAGE DROP	2.6 V typica	at 100 mA		IA	_					
RESISTANCE	0.1 Ω Initial (Max.)		-	<u> </u>						
CURRENT CONSUMPTION	_		1 Amp at 0.5 Amp at 200 mA at 25 Vdc 200 mA at 25 Vdc							
FREQUENCY	_			47 - 63 Hz —						
CABLE MIN. STATIC		0.630" [16mm]								
BEND RADIUS DYNAMIC					Not Recommended					

#### A CAUTION: DO NOT OVER TIGHTEN SWITCH HARDWARE WHEN INSTALLING!

\*\* WARNING: Do not exceed power rating (Watt = Voltage X Amperage). Permanent damage to sensor will occur.

\*QD = Quick Disconnect; Male coupler is located 6" [152mm] from sensor,

Female coupler to flying lead distance is 197" [5m] also see Cable Shielding specification above

REPLACEMENT OF QD SWITCHES MANUFACTURED BEFORE JULY 1, 1997: It will be necessary to replace or rewire the female end coupler.



Reed Switch Life Expectancy: Up to 200,000,000 cycles (depending on load current, duty cycle and environmental conditions) BBS

\*Shielded from the female quick disconnect coupler to the flying leads. Shield should be terminated at flying lead end.

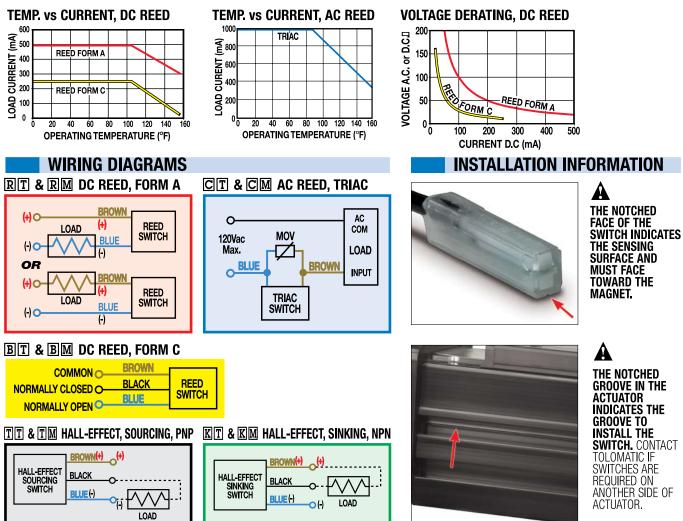
<sup>§</sup> Maximum current 500mA (not to exceed 10VA) Refer to Temperature vs. Current graph and Voltage Derating graph



### **B3S & B3W Electric Rodless Actuators**

### SWITCH PERFORMANCE

### PERFORMANCE

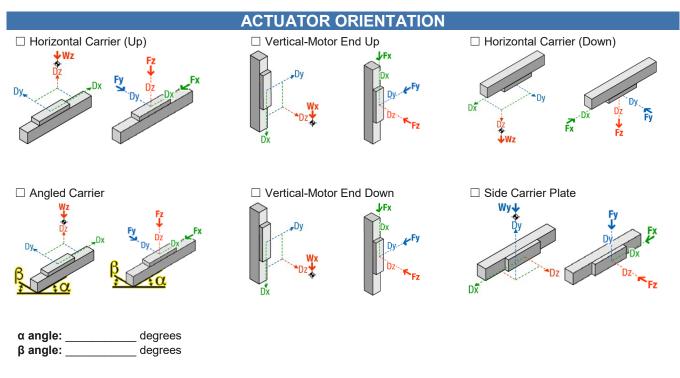






### **Electric Rodless Actuator Application Worksheet**

USE THE TOLOMATIC SIZING AND SELECTION SOFTWARE AVAILABLE ON-LINE AT www.tolomatic.com or call Tolomatic at 1-800-328-2174. We will provide any assistance needed to determine the proper actuator for the job.



ACTUATOR REQUIREMENTS				
Stroke length:	$\Box$ inches $\Box$ millimeters			
No. of Cycles:	$\_$ $\Box$ per minute $\Box$ per hour			
Actuator to Hold Position	<b>n:</b> $\Box$ required $\Box$ not required			
If Hold Required:	$\square$ after move $\square$ during power loss			
Motor:  Third Party Moto	or 🗆 Tolomatic Motor			

<b>APPLICATION ENVIRONMENT</b>
--------------------------------

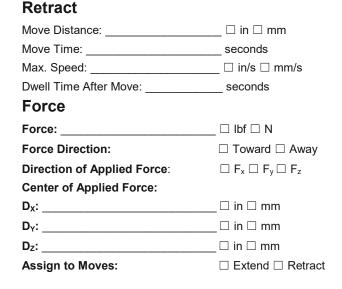
#### Ambient Temperature: \_\_\_\_\_ □ °F □ °C

Actuator Environment Description and Ingress Protection Requirements:

#### **MOTION & FORCES**

#### Extend

Move Distance:	_ $\Box$ in $\Box$ mm
Move Time:	_ seconds
Max. Speed:	_ □ in/s □ mm/s
Dwell Time After Move:	_ seconds
Load	
Load:	_ □ lb □ kg
Supported by Actuator:	_ %
Center of Load:	
D <sub>x</sub> :	$\_\Box$ in $\Box$ mm
D <sub>Y</sub> :	$\_\Box$ in $\Box$ mm
D <sub>z</sub> :	$\_\Box$ in $\Box$ mm
Assign to Moves:	$\Box$ Extend $\Box$ Retract





### SELECTION GUIDELINES

The process of selecting a load bearing actuator for a given application can be complex. It is highly recommended that you contact Tolomatic or a **Tolomatic Distributor for** assistance in selecting the best actuator for your application. The following overview of the selection quidelines are for educational purposes only.

# **CHOOSE ACTUATOR**

Choose an actuator that has the (A) thrust, (B) speed and (C) moment load capacity to move the load. A. Max Thrust: B3S see page B3 11;

B3W see page B3\_25 B. Max. Speed: B3S see critical speed graphs page B3\_13 to B3\_15; All B3W sizes = 200 in/sec (5m/sec).

C. Moment & Load B3S & B3W see page B3 8

#### **COMPARE LOAD TO** MAXIMUM LOAD CAPACITIES

Calculate the application load (combination of load mass and forces applied to the carrier) and application bending moments (sum of all moments Mx, My, and Mz applied to the carrier). Be sure to evaluate the magnitude of dynamic inertia moments. When a rigidly attached load mass is accelerated or decelerated. its inertia induces bending moments on the carrier. Careful attention to how the load is decelerated at the end of the stroke is required for extended actuator performance and application safety. If either load or any of your moments exceed figures indicated in the Moment and Load Capacity table (page B3 8) for the actuator consider:

- 1) Higher capacity bearing style
- 2) A larger actuator size
- 3) Auxiliary carrier
- 4) External guide system

### CALCULATE LOAD FACTOR LF

For loads with a center of gravity offset from the carrier account for both applied (static) and dynamic loads. The load factor (LF) must not exceed the value of 1.5.

 $\frac{Mx}{Mx_{max}} + \frac{My}{My_{max}} + \frac{Mz}{Mz_{max}} + \frac{Fy}{Fy_{max}} + \frac{Fz}{Fz_{max}} \le 1.5$ Mx<sub>max</sub>

If LF does exceed the value of 1.5. consider the four choices listed in step #2.

#### ESTABLISH YOUR **MOTION PROFILE "**AND CALCULATE ACCELERATION RATE

Using the application stroke length and maximum carrier velocity (or time to complete the linear motion), establish the motion profile. Select either triangular (accel-decel) or trapezoidal (accel-constant speeddecel) profile. Now calculate the maximum acceleration and deceleration rates of the move. For the B3S Acceleration/deceleration should not exceed critical speed (page B3\_13) for the screw/nut combination • Select the appropriate numchosen. For the B3W acceleration/deceleration should not exceed 1200 in/sec<sup>2</sup> (30.48 m/ sec<sup>2</sup>). Also, do not exceed safe rates of dynamic inertia moments determined in step #3.

### SELECT THE LEAD SCREW (B3S ONLY)

Based on the application requirements for accuracy, backlash, quiet operation, life, etc. select the appropriate lead screw type (Acme screw with a solid nut or ball screw with a standard or antibacklash nut) and the pitch (lead). For additional information on screw selection, consult "Which Screw? Picking the Right Technology" (#9900-4644) available at www.tolomatic.com.



To help select a motor and drive, use the sizing equations located in the Engineering Resources section [ENGR\_] of the Tolomatic Electric Products Catalog (#3600-4609) to calculate the application thrust and torque requirements. Refer to Motor sections to determine the motor and drive.

#### DETERMINE TUBE SUPPPORT/ **MOUNTING PLATE T-NUT REQUIREMENTS**

- Consult the Tube Support • graph Requirements for the model selected (page B3 9)
- Cross reference the application load and maximum distance between supports
- ber of tube supports, T-nuts or mounting plates and requirements for motor and adapter clearance.

## CONSIDER OPTIONS

- Choose metric or inch (US) Conventional) load mounting. (When ordering use **SK** for inch or **SM** for metric)
- Switches Reed, Solid State PNP or NPN, all available normally open or normally closed.

#### CONSIDER ORIENTATION (B3W ONLY)

Belt drives used in vertical applications will not prevent a load falling in the event of a timing belt failure. A secondary safety measure is recommended if a B3W is used in a safety critical vertical application.

Use the Tolomatic Sizing & Selection Software or call Tolomatic at 1-800-328-2174

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sizeit.tolomatic.com for fast, accurate actuator selection



tolomatic.com/ask Technical support before and after purchase





<b>RDERING</b> base model		O P T I O N S
B3S 20	DBNL02	SK36 LMI DC18 TS2 BM2 TN8
B3S B3S Screw Dr SI 10, 1	L TYPE rive Rodless Actuator ZE 5, 20	MOTOR MOUNTING / REDUCTIONS         (must choose one)         LMI       In-Line mounting         LME23 Ext. shaft for RP & 23 frame motor         LME34 Ext. shaft for RP & 34 frame motor         *LMX       Extended shaft - old style (see note)         *For replacement actuators with extended motor shafts purchased prior to 6/24/02,
D Dual 180° Car NUT/SCREW C	ONIFIGURATION METRIC	shars purchased purchase
(US Conventional) SOLID NUT / PITCH (turn/in) \$SN01 \$SN02, SNA02	MODELS†       SOLID NUT / LEAD (mm/turn)       \$SN12	RPB1       1:1 Reverse-Parallel mount bottom         RPT1       1:1 Reverse-Parallel mount top         RPL2       2:1 Reverse-Parallel mount left         RPR2       2:1 Reverse-Parallel mount right
SN05 SN (Solid Nut) not a BALL NUT / PITCH (turn/in) BN02, BNL02 DN05, DNI 05	BALL NUT / LEAD (turn/in) BNM10	RPT2       2:1 Reverse-Parallel mount top         AUXILIARY CARRIER       FOOD GRADE LUBRICATION         LUB_Grease, Food/Drug
The metric version provi for mounting of the load actuator to mounting su	to the carrier and of the	DCAuxiliary Carrier, then center-to-center spacing desired in inches (SK) or millimeters (SM). (Same unit of measure as stroke length is required) Center-to-center spacing between carriers adds to overall length of the actuator, this distance will not be
SK Str len SM† Str len	oke, enter desired stroke igth in <b>inches</b> oke, enter desired stroke igth in <b>millimeters</b> unting threads and mounting	subtracted from stroke length specified in the previous step. SUPPORTS AND MOUNTING PLATES UPPORTS AND MOUNTING PLATES
fasteners will be eith ing on how stroke le SK=inc	ner inch or metric; depend-	(both may be selected)       database, you can select from over 60 moto manufacturers and hundreds of models.         TS _ Tube Supports plus quantity desired       **MP_Mounting Plates plus quantity desired         **Mounting plates are not available on B3SD Dual 180° models.       Visit www.tolomatic.com/ymh to find you motor/actuator match!

Use Tolomatic Sizing Software to determine available options and accessories based on your application requirements.

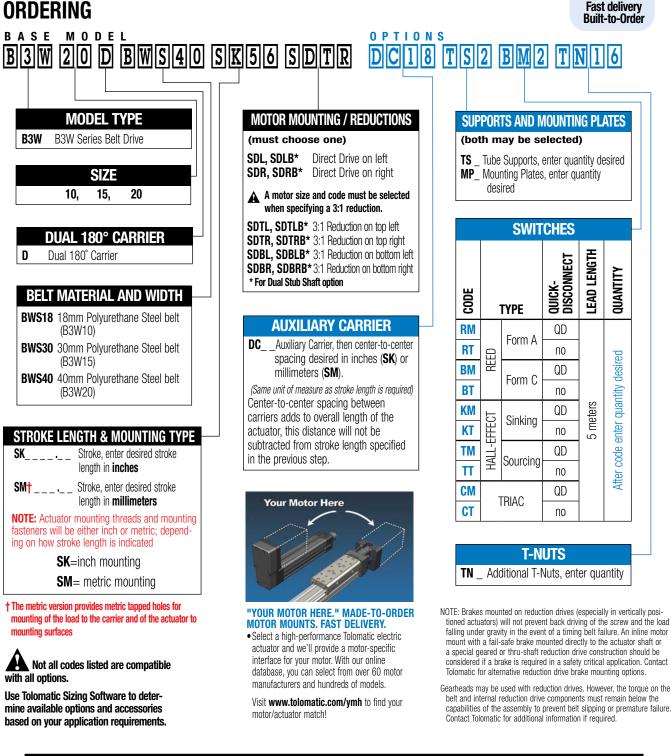
NOTE: Brakes mounted on reduction drives (especially in vertically positioned actuators) will not prevent back driving of the screw and the load falling under gravity in the event of a timing belt failure. An inline motor mount with a fail-safe brake mounted directly to the actuator shaft or a special geared or thru-shaft reduction drive construction should be considered if a brake is required in a safety critical application. Contact Tolomatic for alternative reduction drive brake mounting options.

Gearheads may be used with reduction drives. However, the torque on the belt and internal reduction drive components must remain below the capabilities of the assembly to prevent belt slipping or premature failure. Contact Tolomatic for additional information if required.

FIELD RETROFIT KITS							
ITEM	B3S10_SM	B3S15_SM	B3S20_SM	B3S10_SK	B3S15_SK	B3S20_SK	
Tube Supports	4410-9006	4415-9006	4420-9006	3410-9006	3415-9006	3420-9006	
Tube Supports (B3SD Dual 180° models)	4410-9026	4415-9026	4420-9026	3410-9026	3415-9026	3420-9026	
1/2" Mounting Plates	4410-9030	4415-9030	4420-9030	3410-9142	3415-9056	3420-9056	
1" Mounting Plates	4410-9031	4415-9031	_	3410-9057	3415-9057	_	



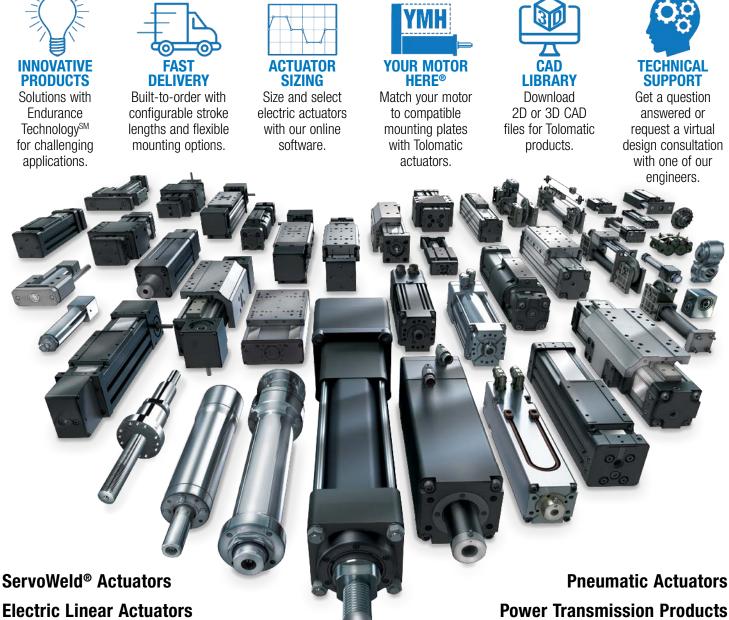
### ORDERING



FIELD RETROFIT KITS								
ITEM	B3W10_SM	B3W15_SM	B3W20_SM	B3W10_SK	B3W15_SK	B3W20_SK		
Tube Supports	4410-9006	4415-9006	4420-9006	3410-9006	3415-9006	3420-9006		
Tube Supports (B3WD Dual 180° models)	4410-9170	4415-9170	4420-9170	3410-9170	3415-9170	3420-9170		
1/2" Mounting Plates (MRV 23-frame motors)	4410-9030	4415-9030	_	3410-9056	3415-9056	_		
1/2" Mounting Plates (MRV all frame motors)	_	_	4420-9030	_	_	3420-9056		
1" Mounting Plates (MRV all frame motors)	4410-9031	_	_	3410-9057	_	_		
1" Mounting Plates (MRV 34-frame motors)	_	4415-9031	_	_	3415-9057	_		

Tolomatic

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MADE IN U.S.A.



COMPANY WITH QUALITY SYSTEM CERTIFIED BY DNV = ISO 9001 = Certified site: Hamel, MN

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