EPSON[®]

Epson[®] GX4C SCARA Robot



Epson GX—taking SCARA performance to the next level.

Ultra high performance and flexibility — high throughput with maxrated payloads and multiple arm configurations to accomplish the most demanding assembly needs

Fast cycle times — high acceleration, smooth motion and fast settling times help maximize throughput with proprietary GYROPLUS[™] vibration reduction system, plus no ringing or overshoot¹

Ultimate ease of use — intuitive and feature-packed Epson RC+[®] development software helps create powerful solutions with a simple user interface, integrated debugger and advanced 3D simulator

Designed for reliability — innovative, compact design handles maxrated workloads at fast speeds and high precision within a small footprint

Low total cost of ownership — includes features that help reduce support and installation costs: batteryless encoders, a built-in Ethernet cable, Epson RC+ software and a rich suite of safety features

Accelerate the development of workcell applications — fully integrated, optional solutions include vision guidance, parts feeding, force guidance, conveyor tracking and fieldbus; Epson RC+ Solutions Platform allows for seamless expansion of third-party solutions, benefiting developers and end users

Increase user interaction without sacrificing productivity — SafeSense[™] technology's standard and advanced safety features, with a proper risk assessment, help allow for increased productivity and worker protection while potentially minimizing machine footprint due to the reduction of physical barriers

Minimize the workcell space requirement with an optimized robot footprint — multiple mount and cable exit options; 250 mm, 300 mm or 350 mm reach available; unique curved arm (350 mm) option maximizes work envelope

Built for demanding environments — Standard, Cleanroom (ISO 3)² and ESD, and standalone ESD models available

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					GX4C SCARA Robot			
Model Name Model Number		GX4-C251x	GX4C SCARA RODOT		GX4-C351x			
Model Number Mounting Type		Tabletop	Tabletop	Multiple	Tabletop	Multiple		
•••		Joint #1 Plus Joint #2						
Arm Length Joint #1 Plus Joint #2		250 mm 300 mm 350 mm						
Repeatability Joints #1 - #2 Joint #3 Joint #4 Doint #4		±0.008 mm ±0.001 mm						
			±0.01 mm					
		±0.005 deg						
Payload Rated Max.		2 kg						
		4 kg						
Standard Cycle Time ³			0.33 sec		4 sec	0.35 s		
		Joint #1	±140 deg	±140 deg	±115 deg	±140 deg	±120 deg	
	Straight	Joint #2 Std Joint #2 Clean	±141 deg ±137 deg	±142 deg ±141 deg	±135 deg	±142 deg		
Max. Motion Range		Joint #1 Right Hand	I			-110 ~ 165 deg		
		Joint #1 Left Hand	-165 ~ 110 deg					
		Joint #2 Right Hand Std & ESD	-1.			-120 ~ 165 deg	-	
	Curved	Joint #2 Right Hand Clean				-120 ~ 160 deg		
		Joint #2 Left Hand Std & ESD				-165 ~ 120 deg		
		Joint #2 Left Hand Clean	-165 ~ 120 deg					
		Joint #3 Std & ESD	150 mm					
	All Models	Joint #3 Clean	120 mm					
		Joint #4						
laint #4 Allawak1-		Rated						
Joint #4 Allowable Moment of Inertia⁴		Max.	0.005 kg·m² 0.05 kg·m²					
		Iviax.						
Joint #3 Downforce				15	150 N			
User Electric Lines				15	5-pin (D-sub), 8-pin (RJ45 Cats	De)		
User Pneumatic Lines Brakes		Ø4 mm x1, ø6 mm x2						
Power		Z axis only						
		AC 200 V – 240 V (single phase)						
Power Consumption		1.2 kVa						
Power Cable Length (Cables Ordered Separately)		3 m/5 m/10 m (straight and angled cable end options)						
Bottom Cable Exit Option (Tabletop Only)		Available	Available	-	Available	-		
Weight (Cables Not Included)		15 kg, 33 lb	15 kg, 33 lb	17 kg, 38 lb	16 kg, 35 lb	17 kg, 38 lb		
Applicable Controller		RC800A						
Installation Environment			Standard/ESD/Cleanroom ISO Class 32 with ESD					
Safety Standards What's Included			TUV Certified to meet ISO 10218-1, UL 1740, CSA Z434, ISO 13849 GX4C robot and RC800A controller, E-Stop unit with cable and connector, cable with flying leads for controller E-stop/Safety connection, connector set (I/O, hand I/O and safety circuit connectors)					
Options								
			Vision Guide		Available			
			IntelliFlex [™] Feeders		Available			
				Force Guide				
			Conveyor Tracking		Available			
			OUTVCYU	Epson RC+ API 8.0				
				+ API 8.0	R19NZ901JK			
					R19NZ901JK R19NZ901JQ			
			Epson RC-	der 8.0				
			Epson RC- GUI Build	der 8.0 Master P, EtherCAT®, PROFINET,	R19NZ901JQ			
			Epson RC- GUI Buik Fieldbus Fieldbus Slave (Ethernet/II	der 8.0 Master P, EtherCAT®, PROFINET, CC-Link)	R19NZ901JQ Available			
			Epson RC- GUI Buik Fieldbus Fieldbus Slave (Ethernet/II PROFIBUS,	der 8.0 Master P, EtherCAT [®] , PROFINET, CC-Link) Point (ECP) 8.0	R19NZ901JQ Available Available			
			Epson RC- GUI Built Fieldbus Fieldbus Slave (Ethernet/II PROFIBUS, External Control Teach P	der 8.0 Master P, EtherCAT [®] , PROFINET, CC-Link) Point (ECP) 8.0 endant	R19NZ901JQ Available Available R19NZ901JL			
			Epson RC- GUI Built Fieldbus Fieldbus Slave (Ethernet/II PROFIBUS, External Control	der 8.0 Master P, EtherCAT [®] , PROFINET, CC-Link) Point (ECP) 8.0 endant for Robotics	R19NZ901JQ Available Available R19NZ901JL Available			

Support

1 When operated within specifications. | 2 Complies with ISO Class 3 (ISO 14644-1) and FED-STD-209D Class 1 cleanroom standards. | 3 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload for tabletop model boost mode (path coordinates optimized for maximum speed). | 4 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using INERTIA command.

Contact:

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