



# EXPERTLY DESIGNED, DELIVERED TO PERFORM

Powered by over 70 years of relentless problem-solving and steadfast reliability, Bishop-Wisecarver delivers innovative motion solutions around the world that thrive in harsh and extreme conditions. Our linear and rotary motion solutions, custom complex assemblies, and embedded intelligence systems lead the manufacturing industry, and they are backed by The **Signature Experience** promise of expert guidance, confidence and customer satisfaction.

#### **EXTENDING ROBOTICS IN CRITICAL APPLICATIONS**

Our solutions use the self-cleaning action of DualVee Motion Technology® for maximum environmental and debris resistance. This ability to excel in harsh and extreme conditions is especially crucial for drilling, welding, painting, and more. Many solutions that run on DualVee guide wheels require no maintenance over the planned life of the machine.

#### **DualVee Guide Wheel Based RTUs Are Ideal For:**



LONG LENGTH



HARSH DEBRIS ENVIRONMENTS



LOW TOTAL COST OF OWNERSHIP



**LOW NOISE** 





#### INTRODUCTION

Both traditional and collaborative robots can benefit from Bishop-Wisecarver 7<sup>th</sup>-Axis Robot Transfer Unit solutions-available in light, medium and heavy capacity. Each system is designed for *durability*, *ease of installation*, and *low total cost of ownership*. Our expert application engineers can help you select the complete 7th axis system solution that is right for you, or customize a solution to meet your exact requirements.

DualVee RTU is suitable for positioning a variety of moderate and heavy robots, but can also provide reliable long-length transfer of non-robot payloads (tooling, retrieval systems, part transfer, etc.) over one or multiple carriages. The DualVee Motion Technology® guides enable smooth-running modular extendibility to grow the system with your needs.

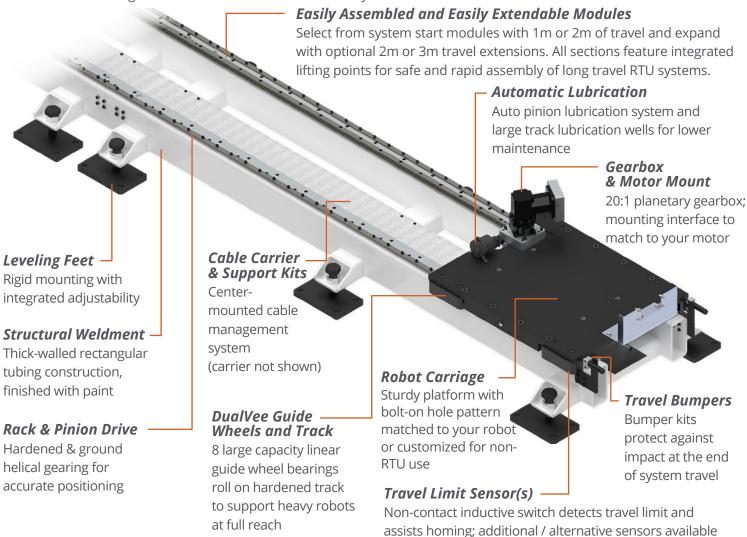


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#### **Features**

The DualVee® RTU is designed from the ground up to provide accurate and durable motion for large robots and cobots. The following features are available on standard systems:



#### **Included Elements:**

- Robust rack-driven module(s)
- Carriage with hole pattern matching your selected robot
- · 20:1 planetary gearbox as standard
- Motor mount matched to your drive motor of choice
- · Homing sensor kit

#### Add-ons:

- Travel bumper kits
- · Additional limit sensor kit
- Cable carrier support kits
- · Drive motor

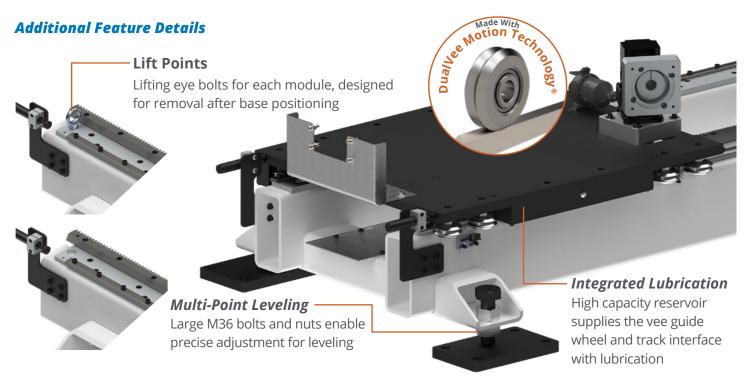
#### **Basic Specs:**

- Max loads of approx. 42.4 kN [11.7 klbf]
- Speeds up to 0.5 m/s [1.64 ft/s]
- Accelerations up to 0.981 m/s<sup>2</sup>
- Accuracy within 0.034 mm / 1 m of travel
- Roll moment stiffness within 0.13 arcmin /1 N-m

#### **Need Customization? Talk to Us!**

- Complete mechatronics solution
- · Removing included elements
- Alternate gearbox
- Cable carrier with pre-installed cables
- · Custom lengths
- · Additional machining or alternate finishing

#### **DUALVEE® RTU OVERVIEW**



#### **Gearbox & Motor Mount Kit**

This kit includes several required elements for driving the DualVee® RTU system. Talk to our Application Engineers to match a gearbox & mount kit to your specified motor. If you require assistance with motor selection, want a customized gearbox, or need a complete mechatronics solution, our experts are here to help!



#### **Included Elements:**

- 20:1 planetary gearbox, 90-degree right angle
- · Motor mounting flange to fit drive motor
- · Shaft coupler to connect to drive motor
- Helical pinion for rack & pinion system
- Automatic lubricator system (125 cc) with felt gear
- · Mounting base with pinion adjustment feature

#### **Gearbox Basic Specs:**

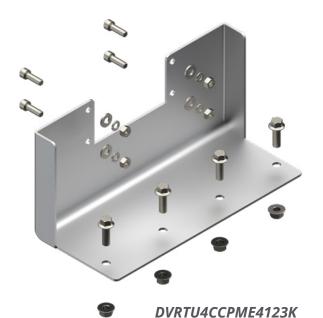
- Backlash: 4 arcmin
- Nominal output torque @ 1500 rpm: 180 Nm
- · Max torque during acceleration: 288 Nm
- Max input speed, continuous: 2500 RPM
- · Max input speed, cyclical: 4500 RPM

#### **Cable Carrier Mounting Kits**

Optional cable carrier mounting kits are available for the DualVee RTU that simplify the attachment of common cable carriers to the moving elements of the RTU for efficient routing of electrical, pneumatic, and other cables. Use flex rated cables to ensure reliability under high-cycle usage. The Igus E4-56-12 cable chain is designed for compatibility and can be included upon request. Contact our Application Engineers if you require a custom cable carrier system.

The mounting bracket is constructed of 1/8" thick AISI 304 stainless steel. The kit includes all necessary hardware for attaching the cable chain and for attaching the bracket to the RTU. The CCME version includes the hardware to attach directly on the top surface of the carriage plate, while the CCPE version includes additional flange nut hardware to attach to the top plate of the pedestal when utilizing that option.

# The moveable end of the cable carrier attaches to the carrier mounting kit on the carriage. Cable Carrier Support Plate The fixed end of the cable carrier attaches to the cable carrier support plate.

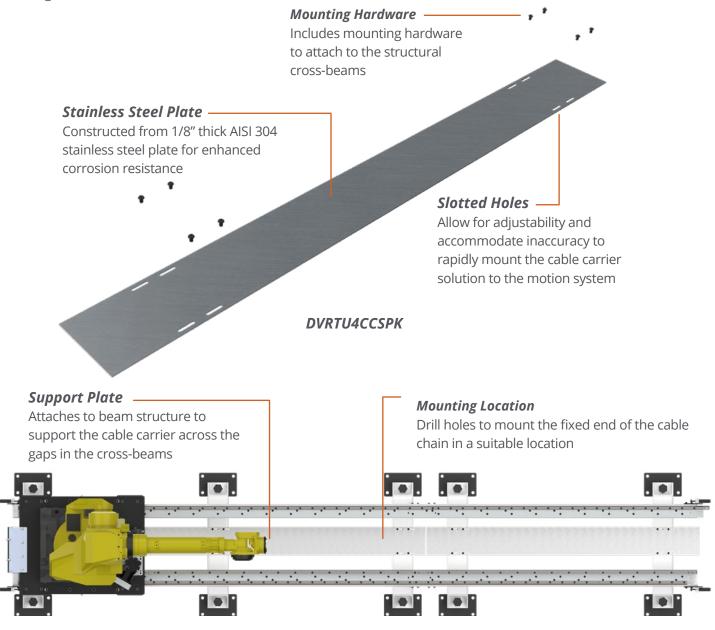


Part Number Scheme										
PREFIX	SIZE	PLATE TYPE	KIT	DESCRIPTION						
D) (DT)	_	CCME4123	K	Carriage Mount						
DVRTU	4	CCPE4123	K	Pedestal Mount						

The carriage mount version attaches directly to the top of the carriage with M10 bolts. The pedestal mount version includes additional M10 flange nuts to attach to the pedestal top plate.

#### **Cable Carrier Support Plate Kit**

The recommended cable carrier is able to operate unsupported over medium distances, but as an option, use the support kit to provide additional support for the cable carrier in the areas that span between the base structure cross-beams. This kit of parts includes the stainless steel plate and all necessary fasteners. Use multiple plate kits to span longer travel distances.



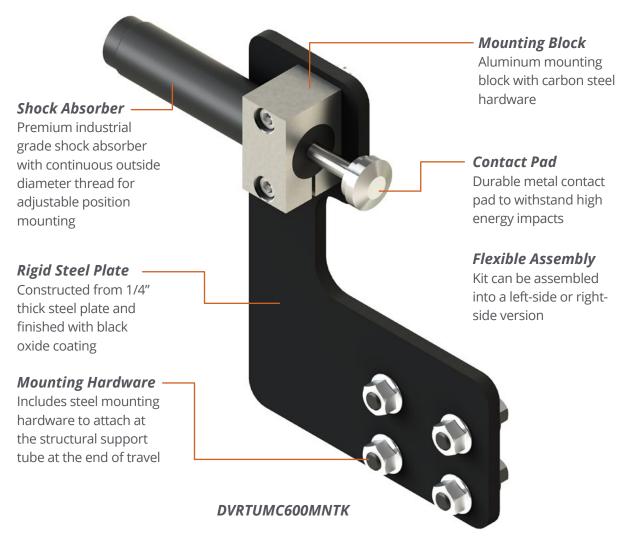
Part Number Scheme								
PREFIX	SIZE	DESCRIPTION	КІТ					
DVRTU	4	CCSP	K					

Longer travel RTU systems will require multiple cable carrier support kits.

STOCK CODE	USE WITH	# OF PLATES	# OF M8X12 FASTENERS	WIDTH (IN)	LENGTH (IN)	THICK (IN)	MASS (LBS)
DVRTU4CCSPK-2000	2m Weldment	1	8	8.00	78.49	0.125	16.9
DVRTU4CCSPK-3000	3m Weldment	2	12	8.00	58.94 x 2	0.125	22.5

#### **Travel Bumper Mounting Kits**

Optional bumpers absorb impact energy at the end of travel in emergency situations to help prevent damage and improve safety. Mounting kits securely attach to the base structure using carbon steel fasteners. Bishop-Wisecarver recommends the use of two bumper kits at each end of travel.



#### **Included Elements:**

- · Steel bracket with black oxide finish
- · Mounting hardware

MC600

Shock absorber with mount block

SHOCK ABSORBER DESCRIPTION

# Part Number Scheme

Not included on RTU system assembly as standard. Add option to order. Each kit contains one shock absorber. Recommended to add four kits per RTU system.

KIT

#### **Basic Specs:**

- Energy capacity of 134 Nm per cycle
- Lifetime use up to 25 million cycles
- Oil dampening with spring return

PREFIX

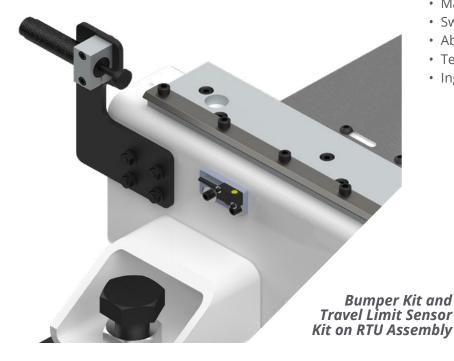
#### **Travel Limit Sensor Kits**

Non-contact inductive proximity sensors are an important option for enhancing the safe operation of any motion system. The standard RTU motion system includes one (1) travel limit sensor (LP4SNSRINDWPOK) mounted on the starting end and is useful for position homing and for end of travel sensing. Add an additional optional sensor at the opposite end of travel to detect over travel conditions and trigger an emergency stop condition that could prevent damage or injury. Choose from a variety of sensor specifications to suit your application.



#### **Included Elements:**

- Proximity sensor with 2 meter cable
- · Mounting hardware
- Adjustable mounting plate



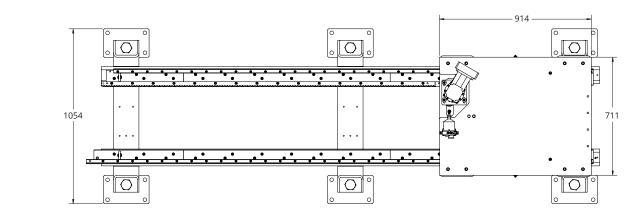
#### **Basic Specs:**

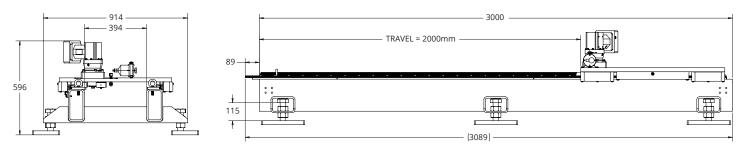
- Operating voltage: 6-30 VDC
- Repeatability: ≤3% sensing dist. (~0.03 mm)
- Hysteresis: <10% sensing dist. (~0.1 mm)</li>
- Voltage drop (sensor on): <1.8 V</li>
- · Max output current: 200 mA
- Switching frequency: 1 kHz
- Absorption at 24 VDC: <12 mA</li>
- Temp. range: -13 to 158 °F (-25 to 70 °C)
- Ingress protection: IP67

Sensor Kits	
SENSOR TYPE	SENSOR KIT STOCK CODE
PNP Normally Open	LP4SNSRINDWPOK (default)
PNP Normally Closed	LP4SNSRINDWPCK
NPN Normally Open	LP4SNSRINDWNOK
NPN Normally Closed	LP4SNSRINDWNCK

#### **DIMENSIONS AND PART NUMBERS**

#### **Overall Dimensions**





All values in mm unless specified.

Foot number and spacing varies with travel length. Contact Bishop-Wisecarver for your specific floor mounting pattern.

Hole pattern not shown; hole pattern dependent on robot, which may impact plate dimensions and overall dimensions; Contact BW for details and updated drawings.

#### **Base System Part Numbers**

Part Nu	ımber Scheme					
PREFIX	TRACK / WHEEL MATERIAL	ROBOT	CARRIAGE W/ PEDESTAL MOUNT	-	TRAVEL LENGTH	LENGTH UNIT
DVRTU	4C (Size 4 carbon steel as standard)	Enter letter from Example Robots table; contact us for other robots	PMA (Blank if robot)	_	Enter value 2 to 8 (1 meter increments)	М

#### **Part Number Examples:**

**DVRTU4CAPMA-1M** = DualVee RTU Starter unit, for ABB IRB 1600, with pedestal, 1 meter travel **DVRTU4CH-2M** = DualVee RTU Starter unit, for Fanuc M-710iC, 2 meter travel

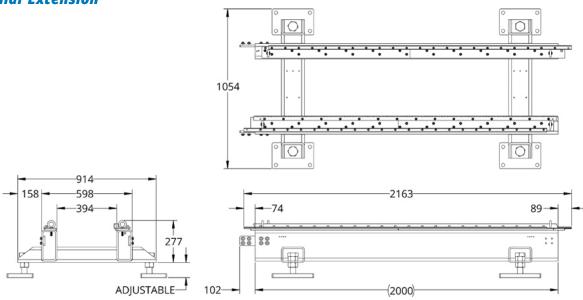
\*Robots listed here are for example only; many more robots can be used with DualVee RTU. Always validate robot application conditions using the sizing calculations on the next page. Contact us to specify robots not listed here.

Disclaimer: All trademarks, logos and brand names are the property of their respective owners. All company, product and service names used in this catalog are for identification purposes only. Use of these names, trademarks, and brands does not imply endorsement.

Example Robots	
MANUFACTURER + MODEL NUMBER*	ROBOT
ABB IRB 1600	А
ABB IRB 2400	В
ABB IRB 2600	С
FANUC M-10iD	Е
FANUC M-20iD	F
FANUC M-710iC	Н
Universal Robotics UR 20	М
Yaskawa GP12	R
Yaskawa GP25	S

#### TRAVEL EXTENSIONS

#### **2M Modular Extension**



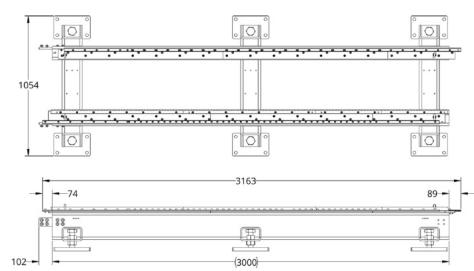
#### **3M Modular Extension**

914 598

277

ADJUSTABLE -

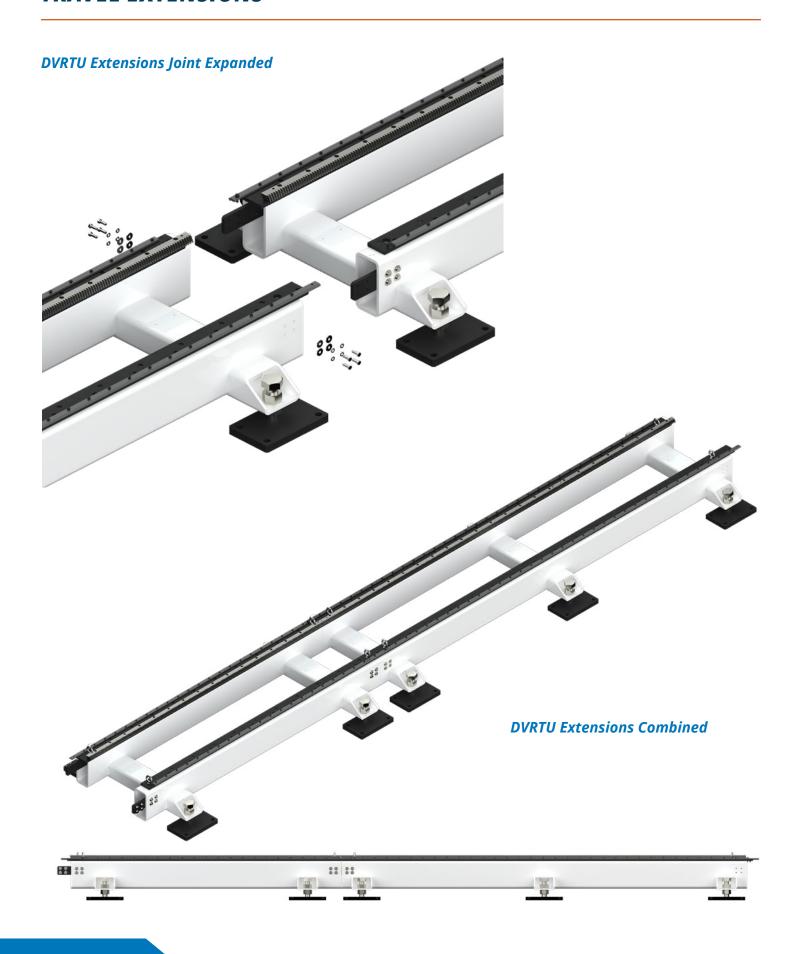
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TRAVEL (M)	STOCK CODE	1M START	2M START	2M EXTENSION	3M EXTENSION
1	DVRTU4C1M	1			
2	DVRTU4C2M		1		
3	DVRTU4C3M	1		1	
4	DVRTU4C4M		1	1	
5	DVRTU4C5M		1		1
6	DVRTU4C6M		1	2	
7	DVRTU4C7M		1	1	1
8	DVRTU4C8M		1		2
CUSTOM	DVRTU4CXXM	Varies	Varies	Varies	Varies



3m Extension / Base for 2m Start



#### **PEDESTAL OPTIONS**

#### **DualVee RTU-H Pedestals**

Pedestal mounted robots enable longer vertical reach with the same robot capacity.

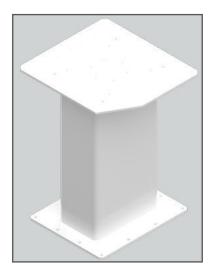
- Reach below the robot base
- Elevate the robot mounting surface above the RTU carriage plate
- Sturdy steel weldment with hardware to adapt robot to RTU
  - Requires RTU carriage plate with machining for pedestal mount
- Predesigned pedestals are available in a variety of standard heights and suitable for all catalog specified robot models
  - 250mm, 500mm, 750mm

Part Nu	ımber Scl	heme								
PREFIX	SIZE	PEDESTAL		TYPE		ROBOT		HEIGHT		
			٨	Single Robot	Н	Fanuc M-710i	1	250mm		
			Α	Sirigle Robot	М	Universal Robots UR20	2	500mm		
DVRTU	4	Р			S	Yaskawa GP25	3	750mm		
			В	3 Multiple Robots		B Multiple Robots	Α	ABB IRB 1600, 2400, 2600	4	1,000mm
					Е	Fanuc M-10iD, M-20iD, Yaskawa GP12				

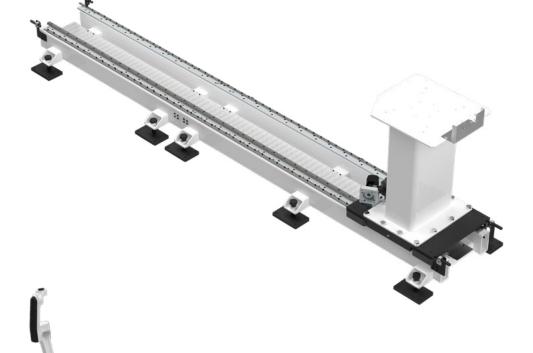
STOCK CODE	DESCRIPTION
DVRTU4PAH1	DualVee RTU Pedestal Assy 250mm Height Robot, M-710iC
DVRTU4PAH2	DualVee RTU Pedestal Assy 500mm Height Robot, M-710iC
DVRTU4PAH3	DualVee RTU Pedestal Assy 750mm Height Robot, M-710iC
DVRTU4PAH4	DualVee RTU Pedestal Assy 1M Height Robot, M-710iC
DVRTU4PAM1	DualVee RTU Pedestal Assy 250mm Height Robot, UR20
DVRTU4PAM2	DualVee RTU Pedestal Assy 5000mm Height Robot, UR20
DVRTU4PAM3	DualVee RTU Pedestal Assy 750mm Height Robot, UR20
DVRTU4PAM4	DualVee RTU Pedestal Assy 1M Height Robot, UR20
DVRTU4PAS1	DualVee RTU Pedestal Assy 250mm Height Robot, GP25
DVRTU4PAS2	DualVee RTU Pedestal Assy 500mm Height Robot, GP25
DVRTU4PAS3	DualVee RTU Pedestal Assy 750mm Height Robot, GP25
DVRTU4PAS4	DualVee RTU Pedestal Assy 1M Height Robot, GP25
DVRTU4PBA1	DualVee RTU Pedestal Assy 250mm Height Robot, IRB 1600, 2400 and 2600
DVRTU4PBA2	DualVee RTU Pedestal Assy 500mm Height Robot, IRB 1600, 2400 and 2600
DVRTU4PBA3	DualVee RTU Pedestal Assy 750mm Height Robot, IRB 1600, 2400 and 2600
DVRTU4PBA4	DualVee RTU Pedestal Assy 1M Height Robot, IRB 1600, 2400 and 2600
DVRTU4PBE1	DualVee RTU Pedestal Assy 250mm Height Robot, M-10iD, M-20iD and GP-12
DVRTU4PBE2	DualVee RTU Pedestal Assy 500mm Height Robot, M-10iD, M-20iD and GP-12
DVRTU4PBE3	DualVee RTU Pedestal Assy 750mm Height Robot, M-10iD, M-20iD and GP-12
DVRTU4PBE4	DualVee RTU Pedestal Assy 1M Height Robot, M-10iD, M-20iD and GP-12

STOCK CODE	DESCRIPTION
DVRTU4CPMA-1M	Start system, 1m travel, w/ pedestal mount holes
DVRTU4CPMA-2M	Start system, 2m travel, w/ pedestal mount holes

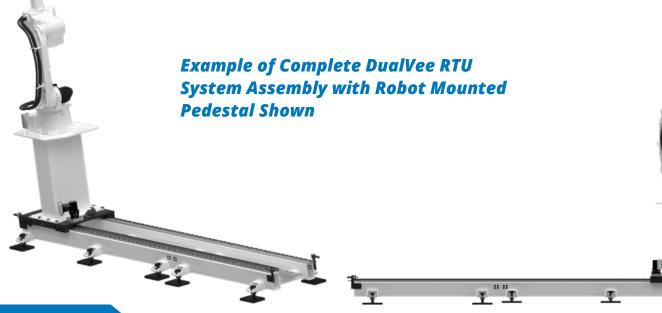
<sup>\*</sup>Stock codes are not pedestal part numbers. Stock codes represent the RTU system with mounting holes to attach to the pedestal.



**PEDESTAL** 



**PEDESTAL WITH FASTENERS** 



#### **Working Load Capacity**

AD	AXII	AL L <sub>A</sub>	RADIAL L <sub>R</sub>		PITCH M <sub>p</sub>		YAW M <sub>y</sub>		ROLL M <sub>R</sub>		THRUST	
TU LO	N	LBF	N	LBF	N-M	LBF-FT	N-M	LBF-FT	N-M	LBF-FT	N	LBF
₹ A	52,416	11,784	57,200	12,859	13,593	10,026	14,834	10,941	12,648	9,328	9,948	7,337

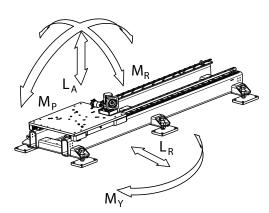
#### **Sizing and Selection Tips**

The following equation is for the purpose of estimating the applied load factor to the wheel plate and track plate only. System drive components are not accounted for, but should also be considered. Working load capacities are based on empirical data on guide wheels used in general applications with static and dynamic load conditions. Guide wheels can routinely achieve travel life of one million cycles or higher when these specified load capacities are observed. For application review, static and dynamic conditions must be considered which include, but are not limited to robot payload, robot motion profile, and worst case dynamic loading conditions.

#### Step 1: Calculate all forces applied to the wheel plate

Any forces applied on the wheel plate need to be considered, including inertial forces, gravitational forces, external forces such as tool pressure, impact loading, and payload. The most conservative calculations will use max foundational loading values from robot manufacturer catalogs.

If assistance is required in resolving specific loads into the resultant forces, please contact our Applications Engineering staff.



#### Step 2: Calculate load factor for the wheel plate

$$L_{F} = \frac{F_{R}}{L_{R}} + \frac{F_{A}}{L_{A}} + \frac{T_{P}}{M_{P}} + \frac{T_{Y}}{M_{Y}} + \frac{T_{R}}{M_{R}} \leq 1$$

**WHERE** 

**L**<sub>E</sub> = Load factor

F<sub>p</sub> = Resultant radial load

**F**<sub>a</sub> = Resultant axial load

T<sub>p</sub> = Resultant Pitch Moment Load

T<sub>v</sub> = Resultant Yaw Moment Load

T<sub>B</sub> = Resultant Roll Moment Load

 $L_R$  = Radial Working Load Capacity

L<sub>a</sub> = Axial Working Load Capacity

M<sub>B</sub> = Pitch Moment Load Capacity

M<sub>v</sub> = Yaw Moment Load Capacity

**M**<sub>R</sub> = Roll Moment Load Capacity

Since the robot can only be extended in one horizontal direction, it is often possible to use  $T_R$  = max applied horizontal moment and  $T_p$  = 0.

If the load factor  $L_{\rm F}$  is >1, consider a larger size system.

### Step 3: Calculate estimated life with adjustment factor

The Life Estimate below shares units with the Life Constant.

Life Estimate = 
$$\left(\frac{L_C}{(L_F)^3}\right)$$
 A<sub>F</sub>

WHERE

 $L_F$  = Load Factor

 $L_C$  = Life Constant

 $A_F$  = Adjustment

Factor

Life Constant L <sub>c</sub>			
WHEEL SIZE	KILOMETERS OF TRAVEL LIFE	INCHES OF TRAVEL LIFE	
4XL	218	8.58 x 10 <sup>6</sup>	

Adjustment Factor A <sub>F</sub>		
CONDITIONS	$A_{\scriptscriptstyle F}$	
Clean, adequate lubrication, low duty, low shock, low vibration	1.0 - 0.7	
Moderate contamination, medium duty, medium shock, low to medium vibration	0.7 - 0.4	
Heavy contamination, limited lubrication, high duty, high acceleration, medium to high shock, high vibration	0.4 - 0.1	



#### **Components & Accessories**

DualVee® MadeWell®

GV3 SL2 PRT2

HDS2 HDRT

MCS

Motor Mounts Gantry Brackets Wrenches

#### Manual Linear Guide Systems

DualVee® UtiliTrak® MinVee® GV3

Simple Select®

SL2 HDS2 MHD HTS

## Actuated Linear Guide Systems

LoPro®
XLA™
ECO60™
SlickStick™
SteadyRail™
HDLS
HDCS
PDU2
DAPDU2
SBD
PSD
SDM

#### **Robot Transfer Units**

DualVee® RTU LoPro® RTU

#### **Custom Solutions**

Extruded Profile Guides Custom Bearings Custom Subassemblies Engineering Services

Large Diameter Ring Guides and Track

#### Rotary Guide Systems

PRT2
DTS2
DTS
DTS+
ALR
HDRT
1-Trak
GFX

DLS





Certified WOSB

#### **Quality Certifications**





- Certified Bay Area Green Business
- Certified Evergreen

#### **Certifications & Compliance**

- EN 9100:2018
- JISQ 9100:2016
- ISO 13485 & GMP Compliance
- Responsible Minerals Initiative
- RoHS
- International Traffic in Arms Regulations Compliant

